TP Series

Intelligent Temperature Controller **User Manual**



Features:

○ Optional input signal types and models.
 ○ With multi-functions of measure display,control output,alarm output,

analog output,RS485 communication and etc. ⊙ Multi types PID control arithmetic can be optional,and with auto-tuning function.

OUsing in industrial machinery, machine tools and masuring instruments.

⊙ Economical and easy operation.

KKTP-BO1E/A2/20201119

∆Warning

- When the failure or abnormal of products lead to a system of major accidents, please set the proper protection circuit in the external.
 Please don't plug in before completing all the wire. Otherwise it may lead to electric shock, fire, fault.
 Not allow to use outside the scope of specification, otherwise it may lead to fire, fault.
 Not allow to use in the place where is inflammable and explosive gas.
 Do not touch power terminal and other high voltage part when the power on, otherwise, you may get an electric-shock.
 Do not remove, repair and modify this product, otherwise it may lead to electric shock, fire, fault.

- The product should not be used in a nuclear facility and human life associated medical equipment.
- The product may occur radio interference when it used at home. You should take adequate countermeasures. 2)
- The product get an electric shock protection through reinforced Insulation. when the product is embedded in the devices and wiring, please subject to the specification of embedded devices
- In order to prevent surge occurs, when using this product in the place of over 30m indoor wiring and wiring in outdoor, you need to set the proper surge suppression 4)
- The product is produced based on mounting on the disk. In order to avoid to touch 5)
- the wire connectors, please take the necessary measures on the product. Be sure to observe the precautions in this manual, otherwise there is a risk of a 6)
- When wiring, please observe the local regulation. To prevent to damage the machine and prevent to machine failure, the product is connected with power lines or large capacity input and output lines and other methods please install proper capacity fuse or other methods of protection circuit. 8)
- Please don't put metal and wire clastic mixed with this product, otherwise it may lead to electric shock, fire, fault. 9)
- 10 Please tighten screw torque according to the rules. If not, it may lead to electric shock and fire.
- 11) In order not to interfere with this products to dissipate heat, please don't plug casing around the cooling vent hole and equipment.
 12) Please don't connect any unused terminal.
 13) Please do the cleaning after power off, and use the dry cleaning cloth to wipe away the dirt. Please don't use desiccant, otherwise, it may casue the deformation or discoleration of the product.
- away the dirt. Please don't use desiccant, otherwise, it may casue the deformation or discoloration of the product.
 14) Please don't knock or rub the panel with rigid thing.
 15) The readers of this manual should have basic knowledge of electrical,control, computer and communications.
 16) The illustration, example of data and screen in this manual is convenient to understand,instead of guaranteeing the result of the operation.

▲ Caution of Install & Connection :

1 Installation :

- 1) This product is used in the following environmental standards. (IEC61010-1)
- Principle of the second 85%RH;Environment condition: Indoor warranty,The altitude is less than 2000m.
- 85%RH;Environment condition: Indoor warranty,The altitude is less than 2000m.
 3) Please avoid using in the following places: The place will be dew for changing temperature; with corrosive gases and flammable gas; with vibration and impact; with water, oil,chemicals, smoke and steam facilities with Dust, salt, metal powder; and with clutter interference, static electric and magnetic fields, noise; where has air conditioning or heating of air blowing directly to the site; where will be illuminated directly by sunlight; where accumulation of heat will happen caused by radiation.
 4) On the occasion of the installation, please consider the following before installation.In order to protect heat saturated, please ensure adequate ventilation space.Please consider connections and environment, and ensure that the products below for more than 50mm space.Please avoid to installed over the machine of the calorific value(Such as heaters, transformer, semiconductor operations, the bulk
- below for more than 50mm space.Please avoid to installed over the machine of the calorific value(Such as heaters, transformer, semiconductor operations, the bulk resistance).When the surrounding is more than 50°C, please using the force fan or cooling fans.But don't let cold air blowing directly to the product.In order to improve the anti interference performance and security, please try to stay away from high pressure machines,power machines to install.Don't install on the same plate with high pressure machine and the product.The distance should be more than 200mm. page 1/8

- 2.Cable caution :

 Please use specified compensation wire in the place of TC input;Please use insulated TC if the measured device is heated metal.
 Please use the cable of lesser resistance in the place of RTD input, and the cable(3 wire) must be no resistance difference, but the total length is within 5m.
 In order to avoid the effect of noise,please put the input signal away from meter cable,power cable,load cable to wiring.
 In order to reduce the power cables and the load power cables on the effect of this product,please use noise filter in the place where easy to effect. You must install it on the grounding of the disk if you use the noise filter, and make the wiring to be shortest between noise filter output side and power connectors.Don't install fuse and switch on the wiring of noice filter output side, otherwise it will reduce the effect of noise filter.

 1 It takes 5s from input power to output. If there is a place with interlocking actions
- circuit signal please use timer relay

- circuit signal, please use timer relay.
 6) Please use twisted pair with a shield for analog output line, to ensure the reliability of signal, if necessary.
 7) Please use twisted pair with a shield for remote RS485 communication cable, and deal with the shield on the host sideearth, to ensure the reliability of signal.
 8) This product don't have the fuse; please set according to rated voltage 250V, rated current 1A if you need; fuse type: relay fuse.
 9) Please use the suitable screw force and crimp terminal. The screw terminal size : M3X8 (with 7.0X7.0 square base) Recommended tightening torque : 0.4N.m Proper cables : 0.25 ~ 1.65mm single cable/multiple core cable
 10) Please don't put the Crimp terminal or bare wire part contact with adjacent connector.
- connector.

Model Illustration



6 I:4 ~ 20mA analog output(can adjust the current output through ACT menu) Blank:No this function

7 4: 48H*48W*71L 7: 72H*72W*71L 8 TP Series temperature controller 6: 96H*48W*71L 9: 96H*96W*71L

There can be optional signal type: 1):TC/RTD/mV/Rt; 2):mA/V.

Ordering Information

Model	Control output	Alarm	Analog 4 ~ 20mA	RS485
TPD-DC18	4 ~ 20mA	2	Yes	Yes
TPD-DC10	4 ~ 20mA	2	Yes	No
TP _D -RC18	Relay	2	No	Yes
TP _D -MC10	Relay/SSR	2	No	No
TP _D -SC18	SSR	2	No	Yes

Specification

1. Electrical parameters:

Sample rate	2 times per second				
Relay capacity	AC 250V /3A, the life of rated load >10W times.				
Power supply	AC/DC 100 ~ 240V(85-265V)				
Power consumption	< 6VA				
Environment	Temperature indoor:0 ~ 50°C,no condensation; Humidity: <85%RH,altitude<2000m				
Storage environment	-10 ~ 60°C,no condensation				
SSR output	DC 24V pulse level,load <30mA				
Current output	DC 4~20mA,load >500Ω,temperature drift250PPM				
Communication port	RS485 port Modbus-RTU procotol, max input 30units				
Insulation impedance	Input, output, power VS meter cover				
ESD	IEC/EN61000-4-2 Contact ±4KV /Air ±8KV perf.Criteria B				
Pulse traip anti-interference	IEC/EN61000-4-4 ±2KV perf.Criteria B				
Surge immunity	IEC/EN61000-4-5 ±2KV perf.Criteria B				
Voltage drop & short interruption immunity	IEC/EN61000-4-29 0% ~ 70% perf.Criteria B				
Isolation pressure-proof	The signal input and output and power 1500VAC 1min;It is DC500V,1min when the low voltage below 60V.				
Total weight	About 300g				
Cover material	The shell and panel frame PC/ABS (Flame Class UL94V-0)				
Panel material	PC				
Power failure memory	10 years times of writing:1 million times				
Panel Protection level	IP65(IEC60529)				
Safety Standard	IEC61010-1 Overvoltage category II, pollution level 2, level II(Enhanced insulation)				

2. Measured signal specifications :

Input type	Symbol	Measure range	Resolution	Accuracy	Input impedance /auxiliary current	communication parameter code	
К	Ч	-50 ~ 1200	1°C	0.5%F.S±3digits	> 500kΩ	0	
J	ŗ	0 ~ 1200	1℃	0.5%F.S±3digits	> 500kΩ	1	
E	E	0 ~ 850	1℃	0.5%F.S±3digits	> 500kΩ	2	
Т	F	-50 ~ 400	1℃	0.5%F.S±2℃	> 500kΩ	3	
page 2/8							

В	ь	250 ~ 1800	2°C	1%F.S±2℃	> 500kΩ	4
R	~	-10 ~ 1700	1℃	1%F.S±2°C	> 500kΩ	5
S	5	-10 ~ 1600	1℃	1%F.S±2℃	> 500kΩ	6
N	0	-50 ~ 1200	1℃	0.5%F.S±1℃	> 500kΩ	7
PT100	P۲	-200 ~ 600	0.2°C	0.5%F.S±0.3℃	0.2mA	8
JPT100	JPE	-200 ~ 500	0.2°C	0.5%F.S±0.3℃	0.2mA	9
CU50	CUSO	-50 ~ 150	0.2°C	0.5%F.S±3℃	0.2mA	10
CU100	CU00	-50 ~ 150	0.2°C	0.5%F.S±1℃	0.2mA	11
0 ~ 50mV	ā!!	-1999 ~ 9999	12bit	0.5%F.S±3digits	> 500kΩ	12
0 ~ 400Ω	۳E	-1999 ~ 9999	12bit	0.5%F.S±3digits	0.2mA	13
*4 ~ 20mA	ā8	-1999 ~ 9999	12bit	0.5%F.S±3digits	100Ω	14
*0~10V	1	-1999 ~ 9999	12bit	0.5%F.S±3digits	>1MΩ	15

* : Need to be ordered.

3.Isolation diagram



"//":Isolation

Note : When the auxiliary power supply between(${\tt I}$)&(${\tt I}$)is used as the power supply of external sensor, if the sensor is non-isolated, it does not isolate.

Panel Illustration



Dimensions (Unit:mm)



Operation Process and Menu Indication

1. Operation process and method





Menu Illustration

:Parameters will keep displaying all the time for all the model and all the setting. Parameters will be hided based on model and menu setting. . . .

No.	symbol	menu name	Description	Set range	Factory s
1	9 81,1	AL1	1st alarm value.Note:the minus is dealed as absolute value when it is as a deviation value.	FL~FH	10
2	891	HY1	1st alarm backlash value	0~1000	1
3	Rdi	AD1	1st alarm type.Note: set the AD1=0, when 1st alarm is used as out2(cooling output). when AD1> 6,alarm 2 will not be acted.	0~12	3
4	ALS	AL2	2nd alarm value.Note:the minus is dealed as absolute value when it is as a deviation value.	FL~FH	5
5	RRS	HY2	2nd alarm backlash value	0~1000	1
6	865	AD2	2nd alarm type,note:the value should set as 0 to close alarm function when the AD1>6.	0~6	4
7	PS	PS	Amend value,display value=actual measured value+ amend value	FL~FH	0
8	lnP	INP	Optional input measured signal type:refer to input signal parameters table. Note: it need to change the relevant parameters after changingSV, AL1,HY1,AL2,HY2,P, OVS,DB	refer to input signal table (page 3)	к
9	οt	от	 0:ON/OFF control; related parameter: DB 1: PID heating control, related parameter: P,I,D,OVS,CP,ST,SPD,PDC 2: ON-OFF cooling control, related arameter DB, when used for compressor cooling control, set parameter: PT 3:PID heating & cooling control. (cooling control OUT2) make output by AL1 relay. related parameters: P, I, D,OVS,CP, CP1,PC,DB,ST,SPD,PDC 4. Over-temperature cooling output, related parameter: DB 5, PID cooling, related parameters: P, I, D, OVS, CP, ST, SPD, PDC 	0~5	1
10	8-7	A-M	Auto-manual control switch : AUTO(0): auto control output MAN(1): manual control output AM(2): manual and auto shift	AUTO~AM	AUTC
11	ρ	Ρ	Proportional band, the less of setting value, the faster of system response conversely, system response slower. P=0, PID control is not valid	0~9999	30
12	I	I	Integral time , the less of the value,the stronger of integral action.Conversely, integral action is lower. I=0, no integral actior	0~9999	120
13	ð	D	Differential time . The higher value, the stronger function of differential.Conversely, lower differential function. D=0, no differential function. Set D=0, when used to control pressure, speed, other quick response system.	0~9999	30
14	oUS	ovs	Overshoot limit, in the process of PID control, when PV>SV+OVS, it force off output; The lower value, the lower PID adjusted range, the worse control stability; please set a proper value according actual state.	0~9999	5
15	CP	СР	OUT1 control cycle,1:SSR control output, 4-200:relay control output.Unit:second	1~200	20
16	CPI	CP1	OUT2 control cycle,cooling relay output cycle.Unit:second	4~200	20
17	PC	РС	OUT2 cooling proportionality coefficient,the higher value,the stronger cooling	1~100	10
18	ರಂ	DB	On-off control backlash(nagetive backlash on-off control)or cooling control and compressor cooling control dead zone. please change value according to decimal position,when you change input sigal type.	-1000~1000	5
19	rca	LCK	Lock function; 0001:SV value can not be modified, 0010:menu settingvalue only can be checked ,cannot modified. 0033: can enter to advanced menu. 0123: menus reset to factory setting.	0~9999	0

2. Advanced Menu Illustration

20	ACE	ACT	Control output mode, 0:relay output; 1: SSR output control. 2:4-20mA control outpuy, please note that for TF3,TF4,TF7. 3: set ACT as 3 to change 4-20mA to analog output.	0~2 (0~3)	0
21	REI	AE1	1st alarm extensions (refer to alarm extend function table page8)	0~5	0
22	885	AE2	2nd alarm extensions (refer to alarm extend function table page8)	0~5	0
23	dр	DP	Decimal point setting , TC/RTD iput , only can set 1 decimal point	0~3	0
24	dbr	DTR	PV fuzzy tracking value, it can get a stable control display value in some status. Note: when the alarm setting value is equal with SV setting value after setting the DTR value, operation of alarm output is subject to actual measured value.Setting 0 to close the function.	0.0~2.0 (0~20)	1.0 (10)
25	ۍ ۲	FT	Filter coefficient, the higher of value, the stronger of filter function	0~255	10

page 4/8

					_
26	Ub	UT	Temperature unit:°C: degrees Celsius F:Fahrenheit	°C°F	°C
27	ԲԼ	FL	Measure range low limit,the setting value must be less than measure range high limit.	Refer to input signal table	-50
28	۶ĸ	FH	Measure range high limit,the setting value must be more than measure range low limit.	Refer to input signal table	1200
29	brt	BRL	Analog range low limit . Note: it also support reserse analog output function.	FL~FH	-50
30	brX	BRH	Analog range high limit. Note: it also support reserse analog output function.	FL~FH	1200
31	oll	OLL	Current output low limit amplitude, limit the current output low limit amplitude.	-5.0~100.0	0
32	oLH	OLH	Current output high limit amplitude, limit the current output high limit amplitude.	0.0 ~ 105.0	100.0
33	SE	ST	Power on auto-tuning switch . 0: normal control after power on 1:enter to PID auto-tuning status after power on . Long press AT key to exit the auto-tuning	0~1	0
34	SPJ	SPD	PID control speed adjustment,optional 0(N)no function,1 (S) slow,2(ss)medium slow, 3 (SSS) very slow,4 (F) fast,5 (FF) medium fast,6 (FFF) express	0~6	N
35	996	PDC	Optional PID type: 0(FUZ):Advanced fuzzy PID arithmetic; 1(STD):normal PID arithmetic	0~1	FUZ
36	PΈ	PT	Starting delay time of compressor, unit:second	0~9999	0
37	683	BAD	RS485 communication baud rate 0(4.8):4.8K;1(9.6):9.6K	0(4.8K) 1(9.6K)	9.6K
38	Rdd	ADD	Communication Address	0~255	1
39	9FC	DTC	Sequenced transport of communication data and setting 000 of response delay;1st is function reserve, 2nd is byte sequenced exchange, 3rd is response delay, it can set 0~9 to 10~100ms.	Refer to communciation procotol ②	0
40	C 88	CAE	User auto-calibrating enable function,this parameter is only for use of input signal except TC/RTD; Y:user of enable auto-calibrating parameters N:user who don`t use enable auto-calibrating parameters	0(N),1(Y)	N
41	CRL	CAL	Operation of user auto-calibrating low limit input,it is starting,when The "YES" flash after signal input add the low-limit signal. It finishedcalibration of low-limit input signal when it display "OK".	YES/OK	YES
		САН	Operation of user auto-calibrating high limit input,it is starting,when the "YES" flash after signal input add the high-limit signal. It finished calibration of high-limit input signal		YES
42	(88	CAII	It finished calibration of high-limit input signal when it display "OK".		V2.0

(1)

Alarm parameters and output logic diagram: Symbol descriptio : " 😤 "means alarm hystersis, " ^" means SV value "▲" means alarm value

No.	Туре	Alarm output (AL1,AL2 is independent of each other) Image:the hatched section means the alarm action
1	High limit absolute value alarm	
2	Low limit absolute value alarm	
3	%High limit deviation value alarm	SV AL
4	XLow limit deviation value alarm	SV-AL SV
5	%High/low limit deviation value alarm	SV-AL SV A SV+AL
6	imit interval ₩ High/low limit interval value alarm	SV-AL SV+AL
No.	Туре	The following two group of alarm parameters(AL1,AL2) used in combination, AL1 alarm output , AD2 must set to 0
7	High/low limit absolute value alarm	$\begin{array}{c} & & & \\ \hline & & & \\ AL1 & SV^2 & & \\ AL2 \end{array}$
8	XHigh/low limit deviation value alarm	SV-AL1 SV+AL2
9	※Alarm between high limit absolute value and low limit deviation value.	SV-AL1 → SV [^] AL2
10	※Alarm between high limit deviation value and low limit absolute value.	AL1 SV SV+AL2
11	High/low absolute∍ value alarm	
12	✗ High/low limit deviation alarm	۲۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰۰

When the alarm value with deviation alarm set to a negative number, it will deal with it as an absolute value

(2) Alarm extension function table

AE1/AE2 value	Alarm handling mode when show HHHH/LLLL	Remark			
0	The state when alarm keep HHH/LLL in previous time	Power on alarm,alarm does not inhibit (As long as meet the			
1	Forced alarm output	requirement of alarm , make alarm			
2	Forced alarm close	output)			
3	The state when alarm keep HHH/LLL in previous time	Power on alarm, alarm inhibits. (Before PV value reach the set			
4	Forced alarm output	value at the first time,the alarm does			
5	Forced alarm close	not output)			

Key function operation

1 Stop mode operation

1)Under the measure mode, press"k/s" for several seconds to enter stop mode;and on the SV window display "STOP" ,main control output will stop or keep at minimum output 2)under stop mode,short press" R/s" to exit stop mode,short press" «AT " to modify SV

value

3)Under stop mode, alarm output and analog output can work normally. 2. PID Parameter auto-tuning operation:

1)Before auto-tuning, switch off the power supply of control output load at temporary or set the meteras stop mode.

2)Before auto-tuning PV value should meet the requirement: PID heating control,PV value is much lower than SV value,PID cooling control,PV value is much larger than SV value.

3)Before auto-tuning, set the proper alarm value,or remove the alarm effect to avoid the effect of alarm output.

4)Set PID type and SV value; the factory default is PID with fuzzy.

5)Set PID control, please set current output to proper range if it has OLL & OLH output limit; defaultset :OLL=0%,OLH=100%.

6)Exit stop mode or connect load power supply, and long press to enter auto-tuning mode now AT indicator will flash

7)Auto-tuning need a period, to ensure the auto-tuning result, please don't modify parameters or power-off during auto tuning. 8) When AT light is off, it will exit the auto-tuning. PID will update automatcially, and can

 9)During auto-tuning, long press " «AT " key, measure beyond the range, display abnormally, shift"STOP" status, power-off and ect, which will stop the auto-tuning. 10)Note: In the place with current output amplitude limit , it may not get the best PID parameters even after auto-tuning.

11)Experienced users can set a proper PID parameter according to their experience. 3. PID heating & Cooling control operation

1)Set the control mode OT to 3.

2)PID heating control act on OUT1 ; Cooling control act on OUT2.

3)Cooling control OUT2 will make output by AL1 alarm relay.

4)Please set the cooling start offset to a value larger than 5, to ensure the cooling would not affect PID heating control impact. 5)Please set the cooling control cycle CP1 to a proper value, and change the cooling

scaling factor to a proper value. 6)When PV value > SV+DB value,the cooling control start to effect;the bigger value of

PV,the longer output time of OUT2 4. Manual control and automatic control mode switch

1)Enter the normal menu and set the A-M as AM 2)Back to measure and control status , press SET key to switch manual control or automatic control

3)Set as manual control mode , the lower line display shows the output scale : M0~M100 according to (0%~100%), press increase and decrease key to adjust the output scale

4)Before switch manual control to auto-control, can press left key to modify the SV value to get better control result

5) If set it as AM status, meter will work as manual control mode after power on and output 0%.

5. Fixed control output mode 1)Set A-M menu as MAN

2)Back to measure and control interface , can adjust the output scale by manual.

3)It will reset to manual output scale after power on again.

 Signal linear auto-tuning function operation
 Set up the INP type,and ensure one of inputs(0-50mV,RT(0-400Ω), 4-20mA and 0-10V).

2)Add the input signal to a proper input channel. 3)Enter menu low-limit to calibrate CAL,press " «AT " to flash "YES" ; and set the input signal to min value and input to meter. 4)When "YES" is flashing,and the min value of signal has input to meter,please press

SET" to ensure and save calibrating value.

5)After calibrating low-limit, enter the high limit to calibrate CAH in menu, and flash YFS

6)Set the input signal to max value to meter and press "SET" to ensure and save the calibrating value when the "YES" is flashing.
 7)After calibrating, it can enter CAE, and change "N" to "Y" then it can use calibrating

value, or it will use the factory default value. 8)The linear signal value of high-limit input should not great than the inout standard value

range ±10%

Connection







NOTE: If any difference here, please subject to the connection of meter.

Methods of simple fault

Display	Methods
	Checks whether the input disconnection and whether normal of FH value,FL value,working environment temperature and whether input signal is selected correctly.

Communication procotol

Meter adopt RS485 Modbus RTU communication protocol, RS485 half duplex communication.Read function code:0x03,write function code 0x10/0x06.Adopts 16 digit CRC check, the meter does not return for error check.

Data frame format:

Start bit	Data bit	Stop bit	Check bit	
1	8	1	No	

Abnormal communication processing : When abnormal response,put 1 on the highest bit of function code.For example:Host request function code 0x03, and slave response function code should be 0x83. Error code:

0x01—IIIegal function: the function code sent from host is not supported by meter. 0x02—IIIegal address: the register address designated by host beyond the address range of meter

0x03—Illegal data: Date value sent from host exceeds the corresponding data range of meter. Communication cycle:

Communication cycle is the time from host request to slave response data . ie: communication cycle=time of request data sending +slave preparation time + response delay time + response return time

Eg:9600 Baud rate:communication cycle of single measured data≥250ms.

1, Read register

For example: Host reads integer SV(set value 200)

The address code of SV is 0x2000, because SV is integer(2 dyte), seizes 1data register.The memory code of 200 is0x00C8 Note:It should read DP value or confirm DP menu value first to ensure the decimal point postion when reading data,and converse the reading data to get the actual value.On the contrary,it should converse the data to corresponding ratio first before writing the data into meter.

	Host request (Read multi-register)									
1	2		3	4	5	6	7		8	
Meter	Func	tion	Start ADD	Start ADD	Data byte	Data byte	XCRC c	code	X CRC	
ADD	code	•	High bit	Low bit	length high bit	length low bi	t low bit		code high bit	
0x01	0x0)3	0x20	0x00	0x00	0x01	0x8F		0XCA	
			Sla	ve norma	answer(Read	multi-register)			
1			2	3	4	5	6		7	
Meter	ADD	Fun	ction code	e Data by number	te Data high bit	Data low bit	XCRC co low bit	ode	<pre>%CRC code high bit</pre>	
0x	01		0x03	0x02	0x00	0xC8 0xB9			0xD2	
Funct	Function code abnormal answer: (For example:host request ADD is 0x2011)									
	slave abnormal answer(Read multi-register)									
	1			2	3	8			9	
Me	eter Al	DD	Fund	ction ID	Error code	XCRC		ЖСІ hiah	RC code	

Meter ADD	Function ID	Error code	low bit	high bit					
0x01	0x83	0x02	0xC0	0xF1					
2 Write multi register									

2.Write multi-register For example:Host use 0x10 function code write SV (setting value 150) ADD code of SV is 0x2000,because SV is integer(2 dyte),seizes 1 data register.The hexadecimal code of 150 is 0x0096

	Host request (write multi-register)										
1	1 2 3		4	5	6	7	8	9	10	11	
Meter ADD	Functio	on Start ADI High bit	D Start ADD Low bit	Length/	Data byte Length/ low bit	Data byte	Data high bit	Data Iow bit	X CRC code low bit	※ CRC code high bit	
0x01	0x10) 0x20	0x00	0x00	0x01	0x02	0x00	0x96	0x07	0xFC	
	Slave normal answer (write multi-register)										
	1	2	3	4	5	6		7		8	
Me AD		Function ID	Start ADD High bit	Start ADD Low bit	Data by Length/ high bit	Lengt	th/ c	<crc ode lov it</crc 	w coc bit	RC le high	
0x	01	0x10	0x20	0x00	0x00	0x0	01	0x0A	()x09	

Host write SV with 0x06 function (setting value 150)

			_		equest (writ					-	
1 2			3 4		5	6		7		8	
ADD I		Function ID		n ADD High bit	ADD Low bit	Data high bi	it Data	hit (XCRC code low bit		%CRC code high bit
0x01 0x0		< 06	0x20 0x00 0x00			0x9	96	0x02		0x64	
	1		2	Slave norm		write si 5	ngle-regi	<u> </u>)		0
				7	4	-	6		жс	/ RC	8 XCRC
AE	eter	er Functior		n ADD ADD D High bit Low bit h		Data high bi	it Dat	Data low bit		e low	code high
	x01		(06	0x20	0x00	0x00	0x		bit 0x02		0x64
	NUT I	0,	.00								0704
	1			Slave abnormal answer (8 9			0
					%CRC code %CRC code				RC code		
	Veter /			unction code	Error code 0x02		IOW DIT				
Poro	0x0		otio	0x86 n address	UXU)2	0x	C3			0xA1
		Add						Read	/		
No.	ref	ectior		Variable name			Register	write		Re	emark
1		2000		Set value S			1	R/W			
2		2001		<u>1st alarm va</u>			1	R/W			
3		2002 2003		<u>1st alarm ba</u> 2nd loop ala			1	R/W R/W	-		
5		2003		2nd alarm b		2	1	R/W	-		
6		2005		Display low		2	1	R/W	-		
7		2006		Display high			1	R/W	+		
8		2007		Analog outp		BRL	1	R/W	-		
9		2008		Analog outp			1	R/W	+		
10	0x:	2009		Control outp	ut low limit	OLL	1	R/W	De	fault w	rith
									De	lecima efault w	
11		200A		Control outp		OLH	1	R/W	10	lecima	l point
12		200B		Overshoot li			1	R/W			
13	UX.	200C		Heat & Cool o		zone DB	1	R/W	_	¢	346
14	14 0x200D			Proportional coefficient of cooling PC			1	R/W		fault w lecima	
15	15 0x200E			Amend PS	-		1	R/W			
16				Dispaly fuzz	y tracking v	alue	1	R	En	gineer	ing work
				DTR					wit	hout de	ecimal point
17		2010				1	R	-	100		
18 19				output scale MV manual-auto control switch A-M		1	R/W R/W	_	<u>100</u>	1: manual	
19	07.	2012		manual-auto		erve	1	17/10	0.	auto	1. manual
20	0x	2100		1st alarm m		CIVC	1	R/W	Т		
21		2101		2nd alarm m			1	R/W			
22	0x:	2102		1st alarm ex	tended mod	de AE1	1	R/W	-		
23	0x:	2103		2nd alarm e	xtended mo	de AE2	1	R/W			
24		2104		Control type	OT		1	R/W			
25	0x:	2105		Control outp	ut mode AC	CT	1	R/W			
26	0x:	2106		RUN STOP	operation		1	R/W	3 :	Run a	2:STP auto-tuning auto-tuning
27	0x	2107	-	Decimal poi	nt DP		1	R/W			0
28	0x	2108		Unit display	UT		1	R/W		(°C)2	6(°F)
29		2109		Filter consta			1	R/W		al a - 1	
30 31		210A 210B		Proportional Integral time		Р	1	R/W R/W			nal point
31		210B 210C		Differential t			1	R/W			mal point
33		210C 210D		Control spe	ed fine-tune	SPD	1	R/W		, acu	
34		210E	+	Heating con	trol cycle C	P	1	R/W	No	o deci	mal point
35		210F		Cooling con			1	R/W	_		mal point
36	0x	2110		Cooling rela	y time PT		1	R/W			mal point
37	0x:	2111	T	Optional inp	ut signal IN	IP	1	R/W	Re	efer to gnal ta	measured
38	0x	2112	+	Meter addre	ss ADD		1	R/W		,	
39		2113		Communica		ate BAD		R	+		
40	0x	2114		Communicati			1	R		No	te ②
41		2115		PID arithme		С	1	R			
42		2116		Lock key LC			1	R	-		
43 44		2117		<u>Meter name</u> Output stati			1	R R	+	No	te ①
		2118		Output statu ad/write	10			71	1	110	u

R:Read ; R/W:Read/write

Note :① Measuring status indication,it means operation when the data position is 1, but it means no opertion when it is 0.

D7	D6	D5	D4	D3	D2	D1	D0
STOP	НННН	LLLL	AT	AL2	AL1	OUT2	OUT1

Note ②: Sequenced transport and response delay of DTC communication data DTC: □ □ - Response delay : 0 ~9 means 10 ~ 100ms Sequenced transport of byte : 0 = 1, 2, 2 = 2, 1

Reserve

%16 digits CRC check code get C program

unsigned int Get_CRC(uchar *pBuf, uchar num)

unsigned i,j;

unsigned int wCrc = 0xFFFF; for(i=0; i<num; i++)

wCrc ^= (unsigned int)(pBuf[i]); for(j=0; j<8; j++)

- - if(wCrc & 1){wCrc >>= 1; wCrc ^= 0xA001; } else
 - wCrc >>= 1;
- }

} return wCrc;

}