# Module Type 4 Channels Temperature Controller

## User Manual

(GTAX 4 Channels Series)

(Dor GTAX-4L A Version)

http://www.toky.com.cn



#### Features:

 $\odot$  Multiple thermocouple signal types for option, weak isolation between signal inputs, able to connect grounding probe; Two wire RTD input.

⊙With many functions, measured display, control output, alarm output, analog output. RS485 communication. etc.

⊙ Optional many types of PID arithmetic, and with auto-tuning function.

⊙ Using for industrial machinery, machine tools, measuring instruments.

⊙ With limiting target value setting function

National High-tech Enterprise/ National Standard Drafting Unit	150	GB	9
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Hotline: 400-0760-168

Version code: KKGTAX-4L-A02E-A/1-20220616

The instruction explain instrument settings, connections, name and etc, please read carefully before you use the temperature controller. Please keep it properly for necessary reference. I. Safe Caution

### A Warning

When the failure or abnormal of products lead to a system of major accidents, please set the proper protection circuit in the external.
 Please don't plug in before completing all the wire.Otherwise it may lead to electric shock, fire, fault.

Not allow to use outside the scope of product specification, otherwise it may lead to fire, fault.

Not allow to use in the place where is inflammable and explosive gas. Do not touch power terminal and other high voltage part when the power on,

6) Do not remove, repair and modify this product, otherwise it may lead to electric

shock, fire, fault. **▲** Caution

1) The product should not be used in a nuclear facility and human life associated medical equipment.

- The product may occur radio interference when it used at home. You should take adequate countermeasures. 2)
- The product get an electric shock protection through reinforced Insulation. When the product is embedded in the devices and wiring, please subject to the 3)
- specification of embedded devices. In order to prevent surge occurs, when using this product in the place of over 30m indoor wiring and wiring in outdoor, you need to set the proper surge suppression circuitry. 4)
- The product is produced based on mounting on the disk. In order to avoid to touch the wire connectors, please take the necessary measures on the 5) product.
- 6) Be sure to observe the precautions in this manual, otherwise there is a risk of a major injury or accident. When wiring, please observe the local regulation.
- To prevent to damage the machine and prevent to machine failure, the product is connected with power lines or large capacity input and output lines and other methods please install proper capacity fuse or other methods of protection circuit. 8)
- protection circuit.
  Please don't put metal and wire clastic mixed with this product, otherwise it may lead to electric shock, fire, fault.
  Please tighten screw torque according to the rules. If not, it may lead to electric shock and fire.

- 10) Please tighten sciew torque according to the rules. In hot, it may lead to electric shock and fire.
  11) In order not to interfere with this products to dissipate heat, please don't plug casing around the cooling vent hole and equipment.
  12) Please don't connect any unused terminal.
  13) Please do the cleaning after power off, and use the dry cleaning cloth to wipe away the dirt. Please don't use desiccant, otherwise, it may casue the deformation or discoloration of the product.
  14) Please don't knock or rub the panel with rigid thing.
  15) The readers of this manual should have basic knowledge of electrical, control, computer and communications.
  16) The illustration, example of data and screen in this manual is convenient to understand, instead of guaranteeing the result of the operation.
  17) In order to use this product with safety for long-term, regular maintenance is necessary. The life of some parts of the equipments are by some restrictions, but the performance of some will change for using many years.
  18) Without prior notice, the contents of this manual will be change. We hope these is no any loopholes, if you have questions or objections, please contact us.

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installation. In order to protect heat saturated, please ensure adequate ventilation space. Please consider connections and environment, and ensure that the products below for more than 50mm space. Please avoid to installed over the machine of the calorific value (Such as heaters, transformer, semiconductor operations, the bulk resistance). When the surrounding is more than 50, please using the force fan or cooling fans. But don't let cold air blowing directly to the product. In order to improve the anti - interference performance and security, please try to stay away from high pressure machines, power machines to install. Don't install on the same plate with high pressure machine and the product. The distance should be more than 200mm between the product and power line. 2. Cable caution:

2. Cable caution:

Cable caution:
 Please use specified compensation wire in the place of TC input;Please use insulated TC if the measured device is heated metal.
 Please use the cable of lesser resistance in the place of RTD input, and the cable(3 wire) must be no resistance difference, but the total length is within 5m.

2) Precise the cable of lesser resistance of the place of KTD input, and the cable(3 wire) must be no resistance difference, but the total length is within 5m.
3) In order to avoid the effect of noise, please put the input dignal away from meter cable, power cable, load cable to wiring.
4) In order to reduce the power cables and the load power cables on the effect of this product, please use noise filter in the place where easy to effect.
You must install it on the grounding of the disk if you use the noise filter, and make the wiring to be shortest between noise filter output side and power connectors. Don't install fuse and switch on the wiring of noice filter output side, otherwise it will reduce the effect of noise filter.
5) It takes 5s from input power to output. If there is a place with interlocking actions circuit signal, please use timer relay.
6) Please use twisted pair with a shield for analog output line, can also connect the common-mode coil to the host side earth, to ensure the reliability of signal.
7)Please use twisted pair with a shield for remote RS485 communication cable, and deal with the shield on't have the fuse; please set according to rated voltage 250V, rated current 1A if you need; fuse type:relay fuse.
9) Please use subable slotted screwdriver and wire.
Terminal distance: 5.0mm. Screwdriver size: 0.6X3.5, length of slotted

Terminal distance: 5.0mm. Screwdriver size: 0.6X3.5, length of slotted screwdriver >130mm. Recommended tightening torque: 0.5N.m. Proper cables: 0.25 ~ 1.65mm single cable/multiple core cable 10) Please don't put the Crimp terminal or bare wire part contact with adjacent

connector.

II Model Illustration

GTAX - 548 - A A:Version

	Blank: TC input R: RTD input (Two wire)
	40: 4 channels input without communication,
	48: 4 channels input with RS485 communication
	S: SSR output T: transistor output
L	Blank: AC/DC 100 ~ 240V power supply F: AC/DC 24V
	GTAX: Module type temperature controller

#### III. General model description

NO	Model	Input Type		OUT1~OUT4	RS485	
	woder	TC	RTD	SSR	Transistor	communication
1	GTAX□-S48	•		•		•
2	GTAX□-T48	•			•	•
3	GTAX S40	•		•		
4	GTAX□-T40	•			•	
5	GTAX□-S48-R		•	•		•
6	GTAX□-T48-R		•		•	•
7	GTAX□-S40-R		•	•		
8	GTAX□-T40-R		•		•	

## **IV.** Specifications

1. Electrical parameters:					
Sample rate	1 times per second per channel				
Power supply	AC/DC 100 ~ 240V (85-265V) or AC/DC 24V				
Power consumption	< 6VA				
Environment	Temperature of indoor: 0 ~ 50°C no condensation, Humidity: <85%RH, altitude<2000m				
Storage environment	-10 ~ 60°C, no condensation				
SSR output	DC 24V pulse level, load<20mA				
Current output	DC 24 DC 100mA per channel				
Communication port	RS485 port, Modbus-RTU procotol				
Insulation impedance	Input, output, power cabinet > 20MΩ				
ESD	IEC/EN61000-4-2 Contact ±4KV /Air ±8KV perf.Criteria B				
Pulse traip anti-interference	IEC/EN61000-4-4 ±2KV perf.CriGTEria B				
Surge immunity	IEC/EN61000-4-5 ±2KV perf.CriGTEria B				
Voltage drop & short interruption immunity	IEC/EN61000-4-29 0% ~ 70% perf.CriGTEria B				
Dielectric strength	Signal input & output & power 1500VAC 1min,below 60V Low voltage circuit between DC500V, 1min				
Total weight	About 400g				
Shell material	PA66-FR (Flame Class UL94V-0)				
Panel material	PVC film and PEM silicone key				
Power-off data protection	10 years , times of writing: 1 million times				
Safety Standard	IEC61010-1 Overvoltage category $II$ , pollution level 2, level $II$ (Enhanced insulation)				

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2.Measurement signal parameter

II	Input Type		Symbol	Measurement Range	Resolution	Accuracy	Input impedance/ Auxiliary current	Commincation Code
	к	K1	61	-50 ~ 1200	1°C	0.5%F.S±3digits	>500kΩ	0
		K2	65	-50.0 ~ 999.9	0.2°C	0.5%F.S±1°C	>500kΩ	16
		J1	ا ل	0~1200	1℃	0.5%F.S±3digits	>500kΩ	1
	J	J2	SC	0.0~999.9	0.2°C	0.5%F.S±1°C	>500kΩ	17
	E	E1	61	0~850	1℃	0.5%F.S±3digits	>500kΩ	2
тс		E2	65	0.0~850.0	0.3°C	0.5%F.S±1°C	>500kΩ	18
	т	T1	E1	-50 ~ 400	1℃	0.5%F.S±3°C	>500kΩ	3
		T2	F5	-50.0~400.0	0.4°C	0.5%F.S±3°C	>500kΩ	19
		В		250~1800	1℃	1%F.S±2℃	>500kΩ	4
		R	<u>ر</u>	-10~1700	1℃	1%F.S±2℃	>500kΩ	5
	S		5	-10~1600	1°C	1%F.S±2°C	>500kΩ	6
	NN		n;	-50 ~ 1200	1℃	0.5%F.S±1°C	>500kΩ	7
		N2	- n S	-50.0 ~ 999.9	0.2°C	0.5%F.S±1℃	>500kΩ	20
	0~50mV		82	-1999 ~ 9999	12bit	0.5%F.S±3digits	>500kΩ	12
	DT400	PT1 PE1		-200.0 ~ 600.0	0.2°C	0.5%F.S±0.3°C	0.2mA	8
	PT100	PT2	PF5	$-200 \sim 600$	1°C	0.5%F.S±3digits	0.2mA	21
	JPT100	JPT1	19FF1	$-200.0 \sim 500.0$	0.2°C	0.5%F.S±0.3℃	0.2mA	9
DTD	JPTIOU	JPT2	7673	$-200 \sim 500$	1°C	0.5%F.S±3digits	0.2mA	22
RTD	CU50	CU51	CUST	$-50.0 \sim 150.0$	0.2°C	0.5%F.S±3°C	0.2mA	10
	0000	CU52	CUS2	$-50 \sim 150$	1℃	0.5%F.S±3°C	0.2mA	23
	01465	CU101	CUOI	$-50.0 \sim 150.0$	0.2°C	0.5%F.S±1℃	0.2mA	11
	CU100	CU102	2003	$-50 \sim 150$	1℃	0.5%F.S±3digits	0.2mA	24
	0~	400Ω	rt.	$-1999 \sim 9999$	12bit	0.5%F.S±3digits	0.2mA	13

Note: RTD input is 2-wire type, and wire resistance compensation is not carried out. The length of the sensor wire shall not exceed 5m, and the wire resistance shall not exceed 0.3Ω, otherwise the measurement accuracy will be affected.

3、Isolation diagram:

	RS485 Port	]
Power Supply	OUT CH1-CH4 SSR Output OUT CH1-CH4 Transistor output	
ouppiy	TC/RTD CH1-CH4 TC Input	

Functional isolation AC 1500V
 Functional isolation DC 500V

#### V. Dimension and installation size



#### VI. Connection

1. Wiring diagram description





VIII. Operation process and menu illustration

1. Operation process & method



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3. Set advanced menu parameters operation



Short Press"SET" Save parameter Short Press" or ">" Modify the parameter to "1"

a. In normal measurement control mode after power on, press and hold the "SET" key for more a in home measurement of the menu parameter viewing mode, short press "EET" key to switch the display channel, the channel number is displayed in the CH indication window, and the panel display correspond to the channel number;

b. In the menu view mode, short press ">" or ">" key check the common menu parameters circularly.

c.In the menu view mode, short press the " **《** " key to flash the viewed menu parameter value to enter the parameter modification mode, and each short press can move one bit to the left; this cycle.

d. In the parameter modification mode, press the " 🛠 " or " 😵 " key once to increase decrease the flashing data bit by one.

e. In the parameter modification mode, shortly press the "SET" key after the parameter is modified to save the modified parameter and long press "SET" exit to the menu view mode.

to save the monined parameter and long press SET exit to the menu view mode. f. In normal measurement control mode, press and hold the " **≪**" key for more than 3 seconds to enter the PID auto-tuning state corresponding to the channel. g. In the normal measurement control mode, press and hold the " **≪**" key for more than 3 seconds to enter or exit the running or stop mode corresponding to the channel; the stop mode SV

window displays "STOP"

#### 1) Common Menu Illustration

Hide parameters according to model

		Hide p	parameters according to model		
No	Symbol	Name	Illustration	Setting range	Factory setting
1		PV	Measuring display value, it will flash or display LLLL/ HHHH when the value overflow measure range.Unit: $C \ / \ F$ or no unit	Refer to measured signal table	NO
2		SV	Control item setting value	SLL~SLH	
3		СН	Channel number display window	1~F	
4	108	LCK	Lock function; 0001: SV value can not be changed; 0010: menu setting value can be read only; 0033: advanced menu can be accessed; 0123: menu restore factory setting	0~9999	0
5	833	ADD	Communication ADD	1~247	1
6	683	BAD	RS485 communication baud rate 4.8 (0) : 4800; 9.6 (1) :9600; 19.2 (2) :19200; 38.4 (3) :38400	0~3	1
7	P-88	PRTY	Communication parity check setting 0: NO 1 : ODD 2 : EVEN	0~2	0
8	986C	DATC	Communication data transport sequence 000; 1st bit function reserved; 2nd bit is byte sequence exchange; 3rd bit function reserved.	Refer to COM protocol note3	0
9	90	ОТ	Contral mode, 0:ON/OFF heating control,1: PID heating control 2: ON/OFF cooling control 3:Reversed 4: Over temperature cooling output 5. PID cooling	0~5	1
10	p	Р	Proportional band, the smaller the value is, the faster the system responds, otherwise, it is slower. When P=0, no PID control, unit same as PV	0~9999	30
11	:	I	Integral time, the smaller the value is, the stronger the integral action is, otherwise, it is weeker. When I=0, no integral action, unit: s.	0~9999	120
12	9	D	Integral time, the smaller the value is, the stronger the integral action is, otherwise, it is weeker. When I=0, no integral action, unit: s.	0~9999	30
13	8-ā	A-M	Auto-manual control switch, AUTO(0): auto control only; MAN(1): manual control only;	AUTO~AM	AUTO
14	C٩	СР	OUT1 control cycle, 1: SSR control output, 4-200: relay control output. Unit:s	1~200	1
15	66	DB	ON/OFF control hystersis(positive and negative numbers work the same); when OT=3, it is the dead zone for cooling control(positive and negative numbers work differently);after change the INP setting, please change this parameter according to the decimal point position.	0~1000	5
16	6-12	INP	Optional input signal, refer to input signal parameters table. Note: after selecting the signal, pls set corresponding parameters	Refer to measured signal specification	K1
17	PS	PS	Amend value, display value= actual measured value + amend value	-1000 ~ 1000	0
2) [	dvan	ced N		II	
18	RCE	ACT	Control execution mode, 0~1: SSR output control or transistor output	0~1	0
19	95	DP	Decimal point setting is effective under the linear signal input	0~3	0
20	der	DTR	PV fuzzy tracking value, properly set this value on some occasions, it can get a more stable control display value, this value is unrelated with actual measured value. Note:after setting this value, when alarm setting value is equal to SV setting value, alarm output operation is subject to actual measured value. Set as 0 to close this function. The temperature input unit: Engineering Digits	0.0~2.0 0~20	1.0
21	55A	SSM	Press the key on the panel to switch the RUN / STOP, 0: prohibited, 1:OpenThis setting is only related to panel operation, not related with communication	0~1	0
22	SEE	SLL	Lower limit of the target SV range. Over this limit, SV can't be modified	FL~FH	
23	SUR	SLH	SV can't be modified	FL~FH	
			5		

Continued

Cont	inued				
No	Symbol	Name	Illustration	Setting range	Factory setting
24	۶٤	FL	Measure range low limit,the setting value must be smaller than measure range high limit.	Refer to measured signal parameter table	
25	۶x	FH	Measure range high limit,the setting value must be more than measure range low limit.	Refer to measured signal parameter table	
26	۶٤	FT	Filter coefficient of each channel, the larger the value, the stronger the filtering effect.	0 ~ 255	10
27	95	PT	Compressor start delay time, unit: s	0 ~ 9999	0
28	98C	PDC	PID type selection 0 (FUZ): advanced fuzzy PID algorithm;1 (STD): ordinary PID algorithm	FUZ/STD	FUZ
29	Unit	UNIT	Temperature unit setting C: Celsius F: Fahrenheit, note: this unit setting is only for temperature measurement signals	(25)°C (26)°F	(25)°C
30	8-5	PRS	Setting parameter reserve position: 0 (EEP):EEPROM with power failure protection; 1(RAM): RAM without power failure protection. Description of setting parameter storage location: EEP and RAM. EEP means that the setting parameters are written into EEPROM and can be permanently saved after power failure.It is generally used for factory setting parameters of equipment. Because EEPROM has the limit of writing times, too many and too frequent writes will be damaged;	EEP/RAM	EEP
31	-95	RSS	RUN/STOP reserve position:0 (EEP): EEPROM with power failure protection; 1(RAM): RAM without power failure protection.	EEP/RAM	EEP
32	ძი	DN	Display the number of channels, indicating the number of measurement channels actually used by the instrument	1~4	4
33	<i>8-</i> 5	DNS	Display the starting channel number, which is used to indicate number of channel 1 in multimachine application. For example: when DNS=3, CH3 $\sim$ CH6 represent 1 $\sim$ 4 channels respectively	1~12	1
34	dht	DNT	Channel cycle display time, 0 means cancel automatic cycle display, unit:s	0~99	4
35	668	BLT	Backlight delay setting, set to 0 when the backlight is always on, otherwise the backlight will be off after the delay	0~10	5
36	1267	VER	Software version.		

#### IX. Key function operation

1. Monitoring mode operation(RUN/STOP)

1) SSM is set in open panel operation; Otherwise, the settings only be modified during communication. 2) Under the measure mode, long press " A " key to enter the STOP mode, SV window will display

"STOP", main control output will stop or keep the minimum output. 3) Under STOP mode, long press " 余 " key to exit STOP mode, press " ≪ " key to modify SV value. Under STOP mode, alarm output and analog output work normally.

2. PID auto-tune operation:

1) Before auto-tune procedure, please switch off the control output load power, or set the meter as STOP mode.

2) Before auto-tune procedure, PV value should meet below condition: when it is PID heating control, PV needs to be much smaller than SV: when it is PID cooling control, PV needs to be much larger than SV.

3) Before auto-tune procedure, please set a proper alarm value or eliminate the alarm condition, in order to prevent the auto-tune procedure from being affected by alarm output.

4) Set PID type and SV value; the factory default setting is fuzzy PID

Set as PID control, if there is OLL & OLH output limiting, please set the output to a proper range; factory default setting is OLL=0%, OLH=100%.

6) Exit STOP mode, or switch on the load Power, immediately long press " 🛠 " key to enter auto-tune mode, then the AT indicator light is on.,

7) The auto-tune procedure will take some time, in order not to affect auto-tune result, please don't

modify the parameters or power-off. 8) When AT light goes out, it automatically exits auto-tune mode, PID parameters will be updated automatically, and then the meter will control automatically and exactly.

9) During the auto-tune procedure, below actions will cause the termination of the precess, long press ≪ " key, measure beyond the scope, abnormal display, switch to STOP mode, power-off, etc.

10) Note: In the occasions with output limiting operation, sometimes, even if the auto-tune is carried out, the best PID parameters still cannot be obtained.

11) Experienced users can set a proper PID parameter according to their experience.

X. Methods of simple fault							
Display info	Method						
LLLL/HHHH	Check whether the input is disconnected; check the FH value and FL value; determine whether the working environment temperature is normal; check whether the input signal selection is correct.						

XI. Communication procotol

The device uses Modbus RTU communication protocol for RS485 half-duplex communication, read function number 0x03, write function number 0x10 or 0x06, adopt 16-bit CRC check, the device does not return check error.

Data frame format: Start bit Data bit Stop bit Check bit Settings in the PRTY menu 8 1 1

Communication abnomal Handling: For abnormal response, set the highest bit of the function number to 1. For example: if the function number requested by the master is 0x03, the corresponding item of the function number returned by the slave is 0x83. Error type code: 0x01 --- Illegal address: The register address specified by the host is not supported by the device. 0x02 --- Illegal address: The register address specified by the host is outside the allowable range of the device parameter address. 0x03 --- Illegal value: The value of the write data sent by the host exceeds the allowable range of the device. Communication cycle: The communication cycle refers to the time from the completion of the master data request

The communication cycle refers to the time from the completion of the master data request to the completion of the slave return data. That is: communication cycle = request data sending time + slave device reply time + response delay time + response return time. Take the 9600 baud rate as an example: the single measurement data communication period is not less than 250ms.

1. Read the register

Example: The host reads the integer SV1 (the given value is 200) The address code of SV1 is 0x200C, the register number is 48205 because SV1 is an integer (2 bytes) and occupies 1 data register. The memory code for decimal integer 200 is 0x00C8

Host request (read multiple registers)									
1	2	3	4	5	6	7	8		
Device Address	Function code		Low start address	High Data of sub-length	Low Data of sub-length	XLow bits of CRC code	%High bits of CRC code		
0x01	0x03	0x20	0x0C	0x00	0x01	0x4F	0xC9		

Slave normal response (read multiple registers)									
1	2	3	4	5	6	7			
Device Address	Function code	Qty of date bytes	High data	Low data	%Low bits of CRC code	%High bits of CRC code			
0x01	0x03	0x02	0x00	0xC8	0xB9	0xD2			
Function number obnormal reasonance:									

r unclor number abnormal response.								
	1	2	3	4	5			
Abnormal	Device Address	Function Number	Error code	%Low bits of CRC code	%High bits of CRC code			
Unsupported function number For example: "01" "02" "04"	0x01	0x83	0x01	0x80	0xF0			
Unsupported data ADD For example: 0x2510	0x01	0x83	0x02	0xC0	0xF1			
Unsupported data value	0x01	0x83	0x03	0x01	0x31			

2. Write to register

For example:Host reads integer SV1 (set value 200)

The ADD code of SV1 is 0x200C, the register number is 48205, because SV is integer(2 dyte), seizes 1 dataregister. The memory code of decimal integer 200 is 0x00C8

Host request (write multi-register)													
1	2	3	4	4 5			6	7	8	9	10		11
	Function code	Start ADD High bit	Sta AD Low	Dİ	Data by Length high bit	Len	gth	Data byte Length	Data high bit	Data low bit	XCF cod low	e	*CRC code high bit
0x01	0x10	0x20	0x0	)C	0x00	C	x01	0x02	0x00	0xC8	0x86	;	0xC8
	Guest normal answer (write multi-register)												
1	2	3		4		5		6	7				8
Mete ADD	r Functic	on Start / High I		Sta Low		Data Lengt high b	h´  L	ata byte ength ow bit	×CI	CRC code			RC code bit
0x01 0x10 0x20			0x	0C	0x00	0	x01	0xCA		0	x0/	A	
Guest	response (	write mult	tiple r	egist	ers)								
				-	1	^		2					-

	1	2	3	4	5
Abnormal	Device Address	Function Number	Error code	XLow bits of CRC code	℅High bits of CRC code
Unsupported function number	0x01	0x90	0x01	0x8D	0xC0
Unsupported data ADD	0x01	0x90	0x02	0xCD	0xC1
Unsupported data value	0x01	0x90	0x03	0x0C	0x01
$  _{a \to b} = \frac{1}{2} \left( \frac{1}{2} + $					

Host write SV (setting value 200)

		Host request (write single-register)						
	1	2	3	4	5	6	7	8
	Meter ADD	Function code	ADD High bit	ADD Low bit	Data high bit		XCRC code low bit	<pre>%CRC code high bit</pre>
	0x01	0x06	0x20	0x0C	0x00	0xC8	0x43	0x9F
[	Guest normal answer (write single-register)							
ĺ	1	2	3	4	5	6	7	8

CRC code CRC code Meter Function ADD Data Data ADD High bit Low bit high bit low bit high bit code low bit 0x01 0x06 0x20 0x0C 0x01 0xC8 0x43 0x9F

Data location error response: (For example:Host request the ADD index is 0x2510) Guest response (write single registers)

	8 8 9				
	1	2	3	4	5
Abnormal	Device Address	Function Number	Error code	XLow bits of CRC code	※High bits of CRC code
Unsupported function number	0x01	0x86	0x01	0x83	0xA0
Unsupported data ADD	0x01	0x86	0x02	0xC3	0xA1
Unsupported data value	0x01	0x86	0x03	0x02	0x61

#### Parameter address mapping table

No	Address (register number ①)	Parameter name	Parameter Decription	Register qty	Read Write	Remark
1	0x2000~0x2003(48193~48196)	PV1~PV4	Measure value	1	R	
2	0x2004~0x2007(48197~48200)	STA1~STA4	Status value	1	R	2
3	0x2008~0x200B(48201~48204)	MV1~MV4	PID Output value	1	R/W	
4	0x200C~0x200F(48205~48208)	SV1~SV4	Setting Value	1	R/W	
5	0x2010~0x2013(48209~48212)	RSA1~RSA4	Power switch	1	R/W	6
6	0x2014~0x2017(48213~48216)	SSM1~SSM4	Panel R/S switch	1	R/W	
7	0x2018~0x201B(48217~48220)	SLL1~SLL4	Set value low limit	1	R/W	
8	0x201C~0x201F(48221~48224)	SLH1~SLH4	Set value high limit	1	R/W	
		Reserve				
9	0x2100~0x2103(48449~48452)	INP1~INP4	Input Type	1	R/W	
10	0x2104~0x2107(48453~48456)	FL1~FL4	Display High limit	1	R/W	
11	0x2108~0x210B(48457~48460)	FH1~FH4	Display low limit	1	R/W	
12	0x210C~0x210F(48461~48464)	DP1~DP4	Decimal point	1	R/W	
13	0x2110~0x2113(48465~48468)	PS1~PS4	Display correct value	1	R/W	
14	0x2114~0x2117(48469~48472)	FT1~FT4	Filter constants	1	R/W	
15	0x2118~0x211B(48473~48476)	DTR1~DTR4	Dispaly tracking value	1	R/W	
		Reserve				
16	0x212C~0x212F(48493~48496)	UNIT1~UNIT4	Display Unit	1	R/W	
17	0x2130~0x2133(48497~48500)	PRS1~PRS4	Set parameter save location	1	R/W	
18	0x2134~0x2137(48501~48504)	RSS1~RSS4	RUN/STOP save location	1	R/W	
19	0x2138(48505)	DN	Display channel qty	1	R/W	
20	0x2139(48506)	DNS	Display starting channel number	1	R/W	
21	0x213A(48507)	DNT	Channel cycle display time	1	R/W	
22	0x213B(48508)	BLT	Backlight delay setting	1	R/W	
Reserve						

23	0x2200~0x2203(48705~48708)	AL11~AL14	Alarm value	1	R/W	
24	0x2204~0x2207(48709~48712)	AD11~AD14	Alarm type	1	R/W	4
25	0x2208~0x220B(48713~48716)	HY11~HY14	Alarm hysteresis	1	R/W	
26	0x220C~0x220F(48717~48720)	AE11~AE14	Alarm extended mode	1	R/W	5
		Reserve				
27	0x2300~0x2303(48961~48964)	OT1~OT4	Control method	1	R/W	
28	0x2304~0x2307(48965~48968)	P1~P4	Proportional band	1	R/W	
29	0x2308~0x230B(48969~48972)	11~14	Integration time	1	R/W	
30	0x230C~0x230F(48973~48976)	D1~D4	Differential time	1	R/W	
31	0x2310~0x2313(48977~48980)	CP1~CP4	Control period	1	R/W	
32	0x2314~0x2317(48981~48984)	DB1~DB2	Bit control hysteresis	1	R/W	
33	0x2318~0x231B(48985~48988)	AM1~AM4	Auto-Manual switch	1	R/W	
		Reserve				
34	0x2324~0x2327(48997~49000)	ACT1~ACT4	Output type	1	R/W	
35	0x2328~0x232B(49001~49004)	PT1~PT4	Cooling relay time	1	R/W	
36	0x232C~0x232F(49005~49008)	PDC1~PDC4	PID Type	1	R/W	
		Reserve				
37	0x2500(49473)	ADD	Communication Add	1	R/W	
38	0x2501(49474)	BAD	Communication baud rate	1	R	
39	0x2502(49475)	PRTY	Communication check bit setting	1	R	
40	0x2503(49476)	DATC	Communication data transmission sequence	1	R	3
41	0x2504(49477)	LCK	Password	1	R	
42	0x2505(49478)	NAME	Software version no.	1	R	

42 Note(1): The register number is the address converted to decimal plus 1 and then the register identification code 4 is added in front; for example: the register number of the data address 0x2000 is 8192 + 1 = 8193 and then 4 is added in front, that is, the register number 48193; Related applications can be seen, such as Siemens S7-200 PLC.

Note (2): Channel status indication. When the data bit is 1, it means execution, and when it is 0, it means not executed.

[	D7	D6	D5	D4	D3	D2	D1	D0
[		НННН	LLLL				AL1	OUT1

Note(3): DTC communication data transmission sequence and response delay description

DATC: 
Byte transfer order: when it is 0, 1, 2, and when it is 1, 2, 1
Reserve
X16-bit CRC check code to get C program

unsigned int Get\_CRC(uchar \*pBuf, uchar num)

}

unsigned i,j;

unsigned int wCrc = 0xFFFF; for(i=0; i<num; i++)

wCrc ^ = (unsigned int)(pBuf[i]); for(j=0; j<8; j++)

if(wCrc & 1){wCrc >> = 1; wCrc ^ = 0xA001; } else

wCrc >>= 1;

return wCrc:

}

④:Alarm logic diagram (read alarm output status by communication): Explanation of symbols: "☆" means HY part, "▲" means alarm value, and "△" means SV value

Alarm code	Alarm form	Alarm output Figure: The shaded area indicates the alarm action
1	Upper limit absolute value alarm	
2	Lower limit absolute value alarm	
3	※ Upper limit deviation alarm	
4	※ Lower limit deviation alarm	$_{SV-AL} _{SV} PV$
5	X Alarm outside upper / lower limit deviation	SV-AL SV SV+AL
6	Alarm within upper / lower limit deviation	→ ☆ ☆ → PV SV-AL SV SV+AL

When the alarm value with deviation alarm is set to a negative number, it is treated as an absolute value.

#### (2) Alarm extension function table

	AE11~AE14 Value	Alarm handling method when it displays HHHH/LLLL	Remark	
Power on, no alarm inhibition	0	Alarm status remains the same	As long as the alarm condition is met, alarm output immediately	
	1	Forced alarm output		
	2	Forced alarm close		
Power on.	3	Alarm status remains the same	After power on and before the PV value reaches	
alarm	4	Forced alarm output	the SV for the first time, the alarm will not output.	
	5	Forced alarm close	After that alarm work normally	

6 : 0: running 1: stopping 2: auto-turning

(upper computer read / write "0" indicates operation, read / write "1" indicates stop, and read / write "2" indicates setting or starting auto-tuning)

XIII. Version and Revision History

Date	Version	Revision content
2021.10.20	A/0 version	1st edition