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Module Type Temperature Controller

For GTE2-B Version



Features:

⊙ Optional input signal types.

⊙With many functions, measured display, control output, alarm output, analog output, RS485 communication, etc.

Optional many types of PID arithmetic, and with auto-tuning function. ⊙ Using for industrial machinery, machine tools, measuring instruments.

⊙ Economical and easy operation.

National High-tech Enterprise/ National Standard Drafting Unit

Version code : KKGTE2-B01E-A/1-20220615

(INA)

The instruction explain instrument settings, connections, name and etc, please read carefully before you use the temperature controller. Please keep it properly for necessary reference.

Safe Caution

Hotline: 400-0760-168

∆ Warning

When the failure or abnormal of products lead to a system of major accidents, please set the proper protection circuit in the external.
 Please don't plug in before completing all the wire. Otherwise it may lead to electric shock, fire, fault.

Not allow to use outside the scope of product specification, otherwise it may lead to fire, fault.

4) Not allow to use in the place where is inflammable and explosive gas.
5) Do not touch power terminal and other high voltage part when the power on, otherwise you may get an electric-shock.
6) Do not remove, repair and modify this product, otherwise it may lead to electric shock, fire, fault.

▲ Caution

1) The product should not be used in a nuclear facility and human life associated medical equipment.

The product may occur radio interference when it used at home. You should take adequate countermeasures.

3) The product get an electric shock protection through reinforced Insulation.
 when the product is embedded in the devices and wiring, please subject to the

specification of embedded devices and wining, please subject to the specification of embedded devices. 4) In order to prevent surge occurs, when using this product in the place of over 30m indoor wiring and wiring in outdoor, you need to set the proper surge suppression circuitry.

5) The product is produced based on mounting on the disk. In order to avoid to touch the wire connectors, please take the necessary measures on the product.
6) Be sure to observe the precautions in this manual, otherwise there is a risk of a major injury or accident.
7) When wiring, please observe the local regulation.
8) To prevent to damage the machine and prevent to machine failure, the product the product is prevent to the product the product is prevent to the product the product is prevent to machine and prevent to machine and the product is prevented the product the product is prevented to the product it prevent to the product it prevent to the product it prevents the product is prevented to the product it prevents the prevent to the product it prevents the prevents the product it prevents the prev

b) To prevent to dramage the machine and prevent to machine and the product is connected with power lines or large capacity input and output lines and other methods please install proper capacity fuse or other methods of protection circuit.
9) Please don't put metal and wire clastic mixed with this product, otherwise it may lead to electric shock, fire, fault.
10) Please tighten screw torque according to the rules. If not, it may lead to electric shock and fire.
11) In order not to interfere with this products to dissipate heat, please don't plus.

shock and tire.
11) In order not to interfere with this products to dissipate heat, please don't plug casing around the cooling vent hole and equipment.
12) Please don't connect any unused terminal.
13) Please don't cleaning after power off, and use the dry cleaning cloth to wipe away the dirt. Please don't use desiccant, otherwise, it may casue the deformation or discoloration of the product.
14) Please don't knock or rub the panel with rigid thing.

 14) Please don't knock or rub the panel with rigid thing.
 15) The readers of this manual should have basic knowledge of electrical,control, computer and communications. 16) The illustration, example of data and screen in this manual is convenient to

16) The illustration, example of data and screen in this manual is convenient to understand, instead of guaranteeing the result of the operation.
17) In order to use this product with safety for long-term, regular maintenance is necessary. The life of some parts of the equipments are by some restrictions, but the performance of some will change for using many years.
18) Without prior notice, the contents of this manual will be change. We hope these is no any loopholes, if you have questions or objections, please contact us.

Installation

Installation

 Installation
 This product is used in the following environmental standards.
 (IEC61010-1) [Overvoltage category II, class of pollution 2]

 This product is used in the following scope:environment, temperature, humidity and environmental conditions. Temperature:0~50°C; humidity: 45~85%RH; Environment condition:Indoor warranty. The altitude is less than 2000m.
 Please avoid using in the following places:

 The place will be dew for changing temperature; with corrosive gases and flammable gas; with vibration and impact; with water, oil, chemicals, smoke and steam facilities with Dust, salt, metal powder; and with clutter interference, static electric and magnetic fields, noise; where has air conditioning or heating of air blowing directly to the site; where will be illuminated directly by sunlight; where accumulation of heat will happen caused by radiation.
 On the occasion of the installation, please consider the following before installation.

installation. In order to protect heat saturated, please ensure adequate ventilation space

Please consider connections and environment, and ensure that the products below for more than 50mm space. Please avoid to installed over the machine of below for more than 50mm space. Please avoid to installed over the machine of the calorific value (Such as heaters, transformer, semiconductor operations, the bulk resistance). When the surrounding is more than 50, please using the force fan or cooling fans.But don't let cold air blowing directly to the product. In order to improve the anti - interference performance and security, please try to stay away from high pressure machines, power machines to install. Don't install on the same plate with high pressure machine and the product. The distance should be more than 200mm between the product and power line. 2. Cable caution

2. Cable caution

Please use specified compensation wire in the place of TC input;Please use insulated TC if the measured device is heated metal.
 Please use the cable of lesser resistance in the place of RTD input, and the cable(3 wire) must be no resistance difference, but the total length is within 5m.

2) Precise the calculation of the second structure in the place of NTD input, and the cable(3 wire) must be no resistance difference, but the total length is within 5m.
3) In order to avoid the effect of noise, please put the input dignal away from meter cable, power cable, load cable to wiring.
4) In order to reduce the power cables and the load power cables on the effect of this product, please use noise filter in the place where easy to effect. You must install it on the grounding of the disk if you use the noise filter, and make the wiring to be shortest between noise filter output side and power connectors. Don't install fuse and switch on the wiring of noice filter output side, otherwise it will reduce the effect of noise filter.
5) It takes 5s from input power to output. If there is a place with interlocking actions circuit signal, please use timer relay.
6) Please use twisted pair with a shield for analog output line, can also connect the common-mode coil to the front-end of the signal receiving device to suppress line interference if necessary, to ensure the reliabilty of signal.
8) This product don't have the fuse; please set according to rated voltage 250V, rated current 1A if you need; fuse type: relay fuse.
9) Please use suitable slotted screwdriver and wire. Terminal distance: 5.0mm. Screwdriver size: 0.6X3.5, length of slotted encember of the signal precise to reade the solution cable, and deal with the shield screwdriver and wire.

Terminal distance: 5.0mm. Screwdriver size: 0.6X3.5, length of slotted screwdriver >130mm. Recommended tightening torque: 0.5N.m. Proper cables: 0.25 ~ 1.65mm single cable/multiple core cable 10) Please don't put the Crimp terminal or bare wire part contact with adjacent

connector



GTE series module type temperature controller Please advise the input signal type when you choose the model. 1st type: TC/RTD/mV/Rt;

nd type: mA/V

III. Ordering Information

Model	Control output function	Alarm	Analog output 4 ~ 20mA	RS485
GTE2-IMC10	SSR, relay output / 4 ~ 20mA	2	Yes	No
GTE2-MC10	SSR, relay output	2	No	No
GTE2-IMC18	SSR, relay output / 4 ~ 20mA	2	Yes	Yes
GTE2-MC18	SSR, relay output	2	No	Yes

IV. Specifications

1. Electrical parameters	S:
Sample rate	2 times per second
Relay capacity	AC 250V /1A lifespan of rated load > 100,000 times(Resistive load)
Power supply	AC/DC 100 ~ 240V (85-265V) or AC/DC 24V
Power consumption	< 6VA
Environment	Temperature of indoor : 0 ~ 50°C no condensation, Humidity : < 85%RH , altitude<2000m
Storage environment	-10 ~ 60°C, no condensation
SSR output	DC 24V pulse level, load<30mA
Current output	DC 4 ~ 20mA load<500Ω, temperature drift 250PPM
Communication port	RS485 port, Modbus-RTU procotol, max input 30 uints
Insulation impedance	Input, output, power cabinet > 20MΩ
ESD	IEC/EN61000-4-2 Contact ±4KV /Air ±8KV perf.CriGTEria B
Pulse traip anti-interference	IEC/EN61000-4-4 ±2KV perf.CriGTEria B
Surge immunity	IEC/EN61000-4-5 ±2KV perf.CriGTEria B
Voltage drop & short interruption immunity	IEC/EN61000-4-29 0% ~ 70% perf.CriGTEria B
Dielectric strength	Signal input & output & power 1500VAC 1min,below 60V Low voltage circuit between DC500V, 1min
Total weight	About 400g
Shell material	PA66-FR (Flame Class UL94V-0)
Panel material	PVC film and PEM silicone key
Power-off data protection	10 years, times of writing: 1 million times
Safety Standard	IEC61010-1 Overvoltage category Π , pollution level 2 , level Π (Enhanced insulation)

2. Measured signal specifications :

Input type	Symbol	Measuring range	Resolution	Accuracy	Input impedance/ auxiliary current	Communi- cation parameter code
К	Ч	-50 ~ 1200	1°C	0.5%F.S±3digits	> 500kΩ	0
J	ſ	0 ~ 1200	1℃	0.5%F.S±3digits	> 500kΩ	1
E	6	0 ~ 850	1℃	0.5%F.S±3digits	> 500kΩ	2
Т	F	-50 ~ 400	1℃	0.5%F.S±3°C	> 500kΩ	3
В	ь	250 ~ 1800	2℃	1%F.S±2℃	> 500kΩ	4
R	ſ	-10 ~ 1700	1°C	1%F.S±2℃	> 500kΩ	5
S	S	-10 ~ 1600	1℃	1%F.S±2°C	> 500kΩ	6
N	C	-50 ~ 1200	1℃	0.5%F.S±1°C	> 500kΩ	7
PT100	P۲	-200 ~ 600	0.2°C	0.5%F.S±0.3℃	0.2mA	8
JPT100	JPF	-200 ~ 500	0.2℃	0.5%F.S±0.3℃	0.2mA	9
CU50	CUSO	- 50 ~ 150	0.2°C	0.5%F.S±3℃	0.2mA	10
CU100	CUOO	-50 ~ 150	0.2°C	0.5%F.S±1℃	0.2mA	11
0 ~ 50mV	52 - 52	-1999 ~ 9999	12bit	0.5%F.S±3digits	> 500kΩ	12
0 ~ 400Ω	-6	-1999 ~ 9999	12bit	0.5%F.S±3digits	0.2mA	13
*4 ~ 20mA	ā8	-1999 ~ 9999	12bit	0.5%F.S±3digits	100Ω	14
*0 ~ 10V	2	-1999 ~ 9999	12bit	0.5%F.S±3digits	>1MΩ	15

* Please note when you choose the model



V. Dimension and installation size



VI. Connection

5

1

2



Note: If there is any change, please subject to the drawing on the meter

VII. Name of universal panel



3

1. Operation process & method



The parameters that will be displayed all the time, no matter what model or setting it is. The parameters that will be hided according to the model function or the setting.

Operation:

a. After power on and under normal measure control mode, long press "SET"

key more than 3s to enter the menu parameters checking mode. b. In the menu checking mode, press "SET" key to check the menu parameters circularly

c. In the menu checking mode, short press "≪" can flash the current menu parameters to enter the parameter modify mode, and every short press can move one position to the left, in this cycle.
d. In the parameter modifing mode, press "≪" or "♥" key once to add or reduce one of flashing data.
a. In the parameter modifing mode, ofter the modification press "CET" to use the set of the parameter modified to the parameter modified to

e. In the parameter modifing mode, after the modification, press "SET" to save the modified parameter, and exit to menu checking mode. f. In the normal measure control mode, short press "≪" to enter SV value

modifing status. The way of modifing SV value is same as that

a) finding status. The way of motining overvations defined as that
b) finding menu parameters.
c) In the normal measure control mode, long press "≪" more than 3s to enter auto-tuning state. During auto-tuning, PV value needs to be lower than SV value.
c) In the normal measure control mode, long press " ≈" key more than 3s to enter or exit monitoring mode, RUN/STOP model.
c) Common menu illustration

No.	Symbol	Name	Illustration	Setting range	Factory setting
1	RL I	AL1	1st alarm value, note: the minus is dealed as absolute value when it is as a deviation value.	FL ~ FH	10
2	891	HY1	1st alarm hystersis	0 ~ 1000	1
3	831	AD1 (1)	1st alarm mode, note: when AL1 is used as OUT2 (cooling output), should set the value AD1=0 (close alarm function). When AD1>6, 2nd alarm function is invalid. Pls refer to "(1) Alarm parameters & output logic diagram"	0 ~ 12	3
4	815	AL2	2nd alarm value, note: the minus is dealed as absolute value when it is as a deviation value.	FL ~ FH	5
5	885	HY2	2nd alarm hystersis	0 ~ 1000	1
6	885	AD2 (1)	2nd alarm mode, pls refer to "(1) Alarm parameters & output logic diagram".	0 ~ 6	4
7	PS	PS	Amend value, display value= actual measured value + amend value	FL ~ FH	0
8	ЪР	INP	Optional input signal, refer to input signal parameters table. Note: after selecting the signal, pls set below relevant parameters: SV, AL1, HY1, AL2, HY2, P, OVS, DB.	Refer to "2" measured signal specification	К
9	ob	OT	Control mode, 0:ON/OFF heating control, relevant parameter: DB. 1: PID heating control, relavant parameters: P, I, D, OVS, CP, ST, SPD, PDC. 2: ON/OFF cooling control, relevant parameter DB; need to set PT when it is used for compressor control. 3:PID heating & cooling control (cooling control OUT2 will output through AL1 relay), relevant parameters: P, I, D, OVS, CP, CP1, PC, DB, ST, SPD, PDC. 4: Over temperature cooling output, relevant parameter: DB 5: PID cooling, relevant parameter: P, I, D, OVS, CP, ST, SPD, PDC.	0 ~ 5	1
10	8-5	A-M	Auto-manual control switch , AUTO(0): auto control only; MAN(1): manual control only; AM(2): auto-manual shortcut switch	AUTO~AM	AUTO
11	ρ	Ρ	Proportional band, the smaller the value is, the faster the system responds, otherwise, it is slower. When P=0, no PID control, unit same as PV	0 ~ 9999	30
12	;	Ι	Integral time, the smaller the value is, the stronger the integral action is, otherwise, it is weeker. When I=0, no integral action, unit: s.	0 ~ 9999	120
13	8	D	Differential time, the greater the value is, the stronger the differential actiontion is, otherwise, it is weeker. When D=0, no differential action. Set D=0 when controlling fast systems, such as pressure, speed, etc, unit: s	0 ~ 9999	30

14	o. 9	ovs	Overshoot limit, during PID control process, when PV(measured value) > SV(set value) + OVS(overshoot limit), force to close output. The smaller this value is, the smaller the PID adjustment range is, the worse the control stability is. Please set the appropriate value according to the actual situation.	0 ~ 9999	5
15	C٩	СР	OUT1 control cycle, 1: SSR control output, 4-200: relay control output. Unit:s	1 ~ 200	20
16	(9)	CP1	OUT2 relay output cycle. Unit: S	4 ~ 200	20
17	PC	PC	OUT2 cooling proportionality coefficient, the higher of value,the stronger of cooling	1 ~ 100	10
18	ძხ	DB	ON/OFF control hystersis(positive and negative numbers work the same); when OT=3, it is the dead zone for cooling control(positive and negative numbers work differently);after change the INP setting, please change this parameter according to the decimal point position.	-1000~1000	5
19	ιCR	LCK	Lock function; 0001: SV value can not be changed; 0010: menu setting value can be read only; 0033: advanced menu can be accessed: 0123: menu restore factory settings	0~9999	0

2. Advanced value illustration

Production Control execution type. U: relay output: 1:SSR output control; 2: 4 - 20mA control output default setting is retransimition output, when set as this type, retrained into its cancelled.) range* setting 21 RE: ACT (default setting is retransimition is cancelled.) 0 - 2 0 22 RE: 2 Control execution type. U: relay output: 1:SSR output control; 2: 4 - 20mA control output default setting is retransimition is cancelled.) 0 - 2 23 #P P Delame extremision function refer to on some occasins, it can get a more stabile control display value, this value is unrelated is subject to actual measured value. Note:after setting (0 - 20) 0.0 24 #Fr Fill Filter function. 0.0 0.0 25 Filt Filter coefficient, the higher of value, the stronger of filter function. 0.0 -255 10 26 U Temperature outif. "C: Celsius degrees filter to must be less than measure range low limit. 0.0 -255 10 26 Filt Filter function. Filter function. Filter function. 10 26 Filt Filter function. Filter function. Filter function. 10 27 Filt Filt Measure range low l	Z. P	uvanc		alue illustration	0.11	-
20 RCE ACT output control; 2: 4 - 20mA control output (default setting is retransimition output, when or -2 0-2 21 RE 15 stalam extensions function; refer to (-1, -2) alarm extensions function; refer to (-2) 0-5 0 22 RE 22 RE 22 RE 0 -5 0 23 AP DP Decimal point setting, maximum 1 decimal place for TC & RTD input 0-3 0 24 & P Decimal point setting, maximum 1 decimal place for TC & RTD input 0-2.0 1.0 24 & F F Filter coefficient, the nighter of value is unrelating value is ounrelating value, alarm output operation is stronger of filter function. 0 -2.0 1.0 25 Ft F Filter coefficient, the highter of value, the stronger of filter function. 0 -2.55 10 26 U UT Terperature unit: "C: Celsius degrees there to maxet range low limit, note: when this value is highter than analog range low limit, this reverse analog output. Net to be parameter table 1200 28 FH H Measure range low limit, note: when this value is highter than analog range low limit, this reverse analog o	No.	Symbol	Name		Setting range	Factory setting
2 RE: AEI 1st alarm extensions function, refer to '22 0 0 0 0 2 RE: 2 2nd alarm extensions function, refer to '22 0	20	ACE	ACT	output control; 2: 4~20mA control output (default setting is retransimition output, when	0~2	
22 RE2 21 alarm extension function, refer to '(2) alarm extension function table''. 0 -5 0 23 dP P Decimal point setting, maximum 1 decimal place for TC & RTD input 0 -3 0 24 dF P Putzzy tracking value, properly set this value on some occasions, it can get a more stable control display value, alter output operation is subject to actual measured value. Set as 0 to close this function. 00 - 2.0 (0 - 2.0) 25 FŁ FT Filter coefficient, the higher of value, the stronger of filter function 0 - 255 10 26 U# UT Temperature unit: "C: Celsius degrees "F: Fahrenheid degrees _i-No unit symbol 7.5, F "C 27 FŁ FH Measure range low limit, note: when this value is higher than analog range low limit. Peter to must be more than measure range low limit. Peter to parameter table 50 28 SH FH Measure analog output. FL-FH 1200 29 S-L RR Analog range low limit, to: when this value is lower than analog range low limit, to FL-FH 1200 30 S-K SFH Cutput high limit, the output low limit curverse ana	21	861	AE1 (2)	1st alarm extensions function, refer to	0~5	0
23 PP Decimal point setting, maximum 1 decimal place for C & RTD input 0-3 0 24 PV fuzzy tracking value, property set this value on some occasions, it can get a more stable control display value, this value is unrelated with actual measured value. Note: after setting this value, value and upput operation is subject to actual measured value. Set as 0 to close this function. 0.0 - 2.0 (10) 25 Ft FT Filter coefficient, the higher of value, the stronger of filter function 0 - 255 10 26 Ut UT Temperature unit: "C: Celsius degrees "C. Ft, - "C 27 Ft. Ft Measure range high limit, the setting value must be less than measure range low limit. Parameter table -50 28 FM FH Measure range low limit, note: when this value is higher than analog range low limit. Ft - FH 1200 29 5-1 RM Analog range low limit, this reverse analog output. FL - FH 1200 30 5-5 ST Output thimit, limit the output low limit ture reverse analog output. Rev to maximum table, strong reading unput set and reverse on 0.0 0 - 105.0 0.0 31 ott. Output thigh limit, limit the output low li	22	538	AE2	2nd alarm extensions function, refer to	0~5	0
24 dtr PV fazzy tracking value, properly set this value on some occasions, it can get a more stable on subject to actual measured value. Set as 0 to close this function. 0.0 - 2.0 1.0 25 Ft FT Filter coefficient, the higher of value, the stronger of filter function 0 2.55 10 26 Ut= UT Temperature unit. "C: Celsius degrees 	23	38	DP	Decimal point setting, maximum 1 decimal	0~3	0
23 Fee Fit Interpretative unit: "C: C: Celsius degrees C: F °C 26 U± UT Temperature unit: "C: C: Celsius degrees °C. F °C 27 Fit. FL Measure range low limit, the setting value Refer to measure signal pranteet table sparameter table 28 FH FH Measure range high limit, the setting value Refer to measure table intervent signal 1200 29 b=t. BRL Analog range high limit, note: when this value FL-FH -50 30 b=r8 BRL Analog range high limit, note: when this value FL-FH 1200 31 oLt. Output wow limit, limit the output low limit FL-FH 1200 31 oLt. Output wow limit, limit the output low limit output high limit, setting 0.0 - 105.0 100.0 33 Sts St ST PID parameters auto-tune status; long press 0~1 0 34 SP4 SP0 Output high limit, etting 01 0 100.0 35 P4 PID agrowthe status-tune. 02 N0 01 0	24	dbr	DTR	PV fuzzy tracking value, properly set this value on some occasions, it can get a more stable control display value, this value is unrelated with actual measured value. Note:after setting this value, when alarm setting value is equal to SV setting value, alarm output operation is subject to actual measured value. Set as 0 to	0.0 ~ 2.0	
26 UI F: Fahrenheit degrees _: No unit symbol U.F U. 27 Fi. FL Measure range low limit, the setting value must be less than measure range high limit. Refer to measure table high limit, the setting value measure table limit, the setting value measure range high limit, tis Refer to measure range high limit, note: when this value is lower than analog range high limit, tis FL-FH -50 29 bs-t. BRL Analog range high limit, note: when this value is lower than analog range high limit, it is FL-FH -50 30 bs-R BRR Analog range high limit, note: when this value is lower than analog range how limit, it is FL-FH 1200 31 cl.t OLt Output high limit the output low limit is thing graater table loss than high limit setting -50100.0 0 32 cl.H OLt Output high limit setting -50100.0 0 33 St: ST PID control speed adjustment,option: 0 (N) no function, 1 (s) slow. 2 (ss) medium slow, 3 (SSS) very slow. 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast 0~-1 0 34 SPd SPD PID control speed adjustment,option: 0 (N) no function nearrow rable with outpower failure protection. 02 9.6 35 P4C PCC PC 0 -2 </td <td>25</td> <td>۶۶</td> <td>FT</td> <td></td> <td>0 ~ 255</td> <td>10</td>	25	۶۶	FT		0 ~ 255	10
27 FL FL FL measure range high limit, the setting value measure range high limit, the setting value must be more than measure range low limit, tote: when this value is higher than analog range high limit, this Refer to measure range high limit, the setting value measure range low limit, it is reverse analog output. Refer to measure range high limit, note: when this value is lower than maalog range how limit, it is FL-FH -50 30 b-r M BRL Analog range high limit, note: when this value is lower than analog range how limit, it is reverse analog output. FL-FH 1200 31 ol.t Output high limit the output low limit to output low limit than high limit exiting graater than low limit setting graater than low limit setting graater than low limit setting the parameter sauct-tune status; long press 0-1 0.0 - 105.0 100.0 33 St: ST PID control speed adjustment,option: 0 (N) no function, 1 (s) slow, 2 (ss) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast 01 0 34 SPd SPD Didagottinu option: 0 (FU2); Advanced fuzzy PID arithmetic; 0-1 FUZ FU2 35 Psd PDD Control speed adjustment,option: 0 (N) no function parameter sauce adjustment,option: 0 (N) no function, 1 (s) slow, 2 (ss) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast 01 0 36 Psd PDD dogottinu option; 10 (EDE); normal PID arithmetic; 0-1 FUZ N0 38	26	UE	UT	Temperature unit: °C: Celsius degrees	°C、°F、_	°C
28 FH must be more than measure range low limit. FL-FH -50 29 b=rt. BR Analog range high limit, note: when this value is higher than analog range low limit. FL-FH -50 30 b=rM BRH is lower than analog range low limit. FL-FH 1200 31 ott. Output low limit, limit the output low limit current amplitude. Setting value must be less than high limit setting -5.0~100.0 0 32 ott.M OLH Output high limit, limit the output high limit. 0.0 ~ 105.0 100.0 33 St ST Output high limit setting 0.0 ~ 105.0 100.0 34 SPd SPD Auto-tune activation after power-on, 0: work normally after power-on, 1: automatically enter PID parameters auto-tune. 01 0 34 SPd SPD Output high limit, notic: 01 01 0 35 PdC DC Output adjustment,option: 0 (N) no function, 1 (s) slow, 2 (s) measured adjustment,option: 0 (N) no function, 1 (s) slow, 2 (S) measured adjustment,option: 0 (N) no functoly peed adjustment,option	27	۶٤	FL		measured signal	-50
29 S-L BRL is higher than analog range high limit, it is reverse analog output. FL-FH -50 30 S-M BRH is lower than analog range low limit, it is reverse analog output. FL-FH 1200 31 S-L Output low limit, limit the output low limit current amplitude. Setting value must be less than high limit setting -5.0-100.0 0 32 s-L Output ligh limit, limit the output high limit current amplitude. Setting value must be greater than low limit setting 0.0 ~ 105.0 100.0 33 St: ST PID parameters auto-tune status; long press <at auto-tune.<="" exit="" key="" td="" to=""> 0-1 0 34 SPd SPD Dentoriol speed adjustment,option: 0 (N) no function, 1 (s) slow, 2 (ss) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast 01 FUZ 35 PdC PDC Optigrithm option: 0 (FUZ): Advanced fuzzy PID arithmetic; 1 (STD): normal PID arithmetic; 1 (STD): 1 ODD 0-2 N0 38 Px-S3 PRTY Communication ADD 0-2 N0 39 Rade ADD Communication ADD 0-2 N0 <td< td=""><td>28</td><td>۶x</td><td>FH</td><td></td><td>measured signal</td><td>1200</td></td<></at>	28	۶x	FH		measured signal	1200
30 br-M BRH is lower than analog range low limit, it is reverse analog output. FL-FH 1200 31 eLL OLL Current amplitude. Setting value must be less than high limit setting -5.0~100.0 0 32 eLH OLH Current amplitude. Setting value must be greater than low limit setting 0.0 ~ 105.0 100.0 33 5E ST Output high limit setting value must be greater than low limit setting 0.0 ~ 105.0 100.0 34 5Fe ST Auto-tune activation after power-on, 0: work normally after power-on, 1: automatically enter PID parameters auto-tune status; long press -AT key to exit auto-tune. 0~1 0 34 5Fe SPD PID control speed adjustment,option: 0 (N) no function, 1 (s) slow, 2 (ss) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast 0~1 FUZ 35 Pat PDC OlfPU2: Advanced fuzzy PID arithmetic; 1 (STD): normal PID arithmetic 0~1 FUZ 36 Pat PT Communication ADD 1~247 1 37 5Rd BAD Baud rate 0 (4.8): 4800 ; 1 (9.6): 9600; 2 (19.2): 19200 0~2 9.6 38	29	5-6	BRL	is higher than analog range high limit, it is reverse analog output.	FL~FH	-50
31 cl.t. OLL current amplitude. Setting value must be less than high limit setting -5.0~100.0 0 32 cl.H. OLH Cutput high limit. current amplitude. Setting value must be greater than low limit setting 0.0 ~ 105.0 100.0 33 St. ST Auto-tune activation after power-on, 0: work normally after power-on, 1: automatically enter PID parameters auto-tune status; long press <at auto-tune.<="" exit="" key="" td="" to=""> 0~1 0 34 SPC SPD PID control speed adjustment,option: 0 (N) no function, 1 (s) slow, 2 (ss) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast 0~1 FUZ 35 PAC PDC Optiontim option: 0(FUZ): Advanced fuzzy PID arithmetic; 0(FUZ): 12(12): 19200 0~2 9.6 38 PA-EM PRT Communication parity check setting , 0: NO 0~2 NO 39 Rade ADD Communication data transport sequence 000; Refer to COM. per tocol. 0 40 det: DC Setting parameter reserve position: 0 (EEP): EEP/RAM EEP 41 PA-5 PRS EEPROM with power failure protection</at>	30	6-X	BRH	is lower than analog range low limit, it is reverse analog output.	FL~FH	1200
32 st.H OLH current amplitude. Setting value must be greater than low limit setting 0.0 ~ 105.0 100.0 33 St: ST Auto-tune activation after power-on, 0: work normally after power-on, 1: automatically enter PID parameters auto-tune. 0~1 0 34 SPd SPD SSD biological auto-tune. 0~1 0 34 SPd SPD OLP control speed adjustment,option: 0 (N) no function, 1 (s) slow, 2 (ss) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast 0~0 0~6 N 35 Psd PDC O(FUZ): Advanced fuzzy PID arithmetic: 1(STD): normal PID arithmetic: 0~1 0~2 9.6 36 Ps- PT Compressor start delay time, unit: s 0~9999 0 37 SRd BAD Baud rate 0 (4.8): 4800 ; 1 (9.6): 9600; 2 (-9.2) 0~2 N0 38 P-t-ty PRT Communication ADD 1~247 1 40 stc DTC Communication ADD 1~247 1 41 P-5 PRS EEPROM with power failure protection; 10 (EEP); EEPRAM EEP 41 P-5 RSS EEPROM with power failure protec	31	oll	OLL	current amplitude. Setting value must be less than high limit setting	-5.0~100.0	0
33 5± ST PID parameters auto-tune status; long press <at auto-tune.<="" exit="" key="" td="" to=""> 0~1 0 34 5₽d SPD PID control speed adjustment, option: 0 (N) no function, 1 (s) slow, 2 (s) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast 0~6 N 35 Past PID algorithm option: 1 (STD): normal PID arithmetic; 1 (STD): noreserve position; 1 (STD):</at>	32	οLΧ	OLH	current amplitude. Setting value must be greater than low limit setting	0.0 ~ 105.0	100.0
34 58-3 SPD function, 1 (s) slow, 2 (ss) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast 0~-6 N 35 8-4C PDC PID algorithm option: 0(FUZ): Advanced fuzzy PID arithmetic; 11(STD): normal PID arithmetic 0~-1 FUZ 36 P+ PT Compressor start delay time, unit: s 0~-9999 0 37 58-8 BAD Baud rate 0 (4.8): 4800 ; 1 (9.6): 9600; 2 (19.2): 19200 0~-2 9.6 38 P-E9 PRT Communication parity check setting , 0~-2 N0 39 84-8 ADD Communication ADD 1~-247 1 40 -5: DTC Is thi function reserved; 2nd bit is byte sequence exchange; 3rd bit function reserved. Inote 3 note 3 41 9-5 PRS EEPROM with power failure protection; 1(RAM); RAM without poweration parameters. N: don	33	SE	ST	normally after power-on, 1: automatically enter PID parameters auto-tune status; long press	0~1	0
35 PSC PDC 0(FUZ): Advanced fuzzy PID arithmetic; 1(STD): normal PID arithmetic 0~1 FUZ 36 P: PT Compressor start delay time, unit: s 0~9999 0 37 SR3 BAD Baud rate 0 (4.8): 4800; 1 (9.6): 9600; 2 (19.2): 19200 0~2 9.6 38 P-E3 PRTY Communication parity check setting , 0 : NO 0~2 NO 39 R34 ADD Communication ADD 1~247 1 40 SEC DTC Communication data transport sequence 000; 1st bit function reserved; 2nd bit is byte sequence exchange; 3rd bit function reserved; 0 Refer to COM, note @ 0 41 P-S PRS EEPROM with power failure protection; 1(RAM): RAM without power failure protection. EEP/RAM EEP 43 SLS BLT Backlight delay time setting, 0: backlight stays on for the setting time, time's up, it turns off. Unit:M 0 ~10 5 44 CRE CAE CAE Self-calibration enable function, this parameter is only for the input signals except N: don' t use the self-calibration parameters. 0 (N) N N 44 </td <td>34</td> <td>SPJ</td> <td>SPD</td> <td>function, 1 (s) slow, 2 (ss) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium</td> <td>0~6</td> <td>N</td>	34	SPJ	SPD	function, 1 (s) slow, 2 (ss) medium slow, 3 (SSS) very slow, 4 (F) fast, 5 (FF) medium	0~6	N
37 5.8.3 BAD Baud rate 0 (4.8): 4800; 1 (9.6): 9600; 0~2 9.6 37 5.8.3 BAD Baud rate 0 (4.8): 4800; 1 (9.6): 9600; 0~2 9.6 38 PRTY Communication parity check setting , 0~2 0.2 9.6 38 PRTY Communication parity check setting , 0~2 0.2 N0 39 B44 ADD Communication ADD 1~247 1 40 SEC DTC Communication data transport sequence 000; Refer to COM, protocol note © 0 41 Pr5 PRS EEPROM with power failure protection; 1(RAM): RAM without power failure protection; 1(RAM): RAM withou	35	P80	PDC	0(FUZ): Advanced fuzzy PID arithmetic;	0~1	FUZ
37 SR3 BAD 2 (19.2): 19200 0.2 9.6 38 PRTY Communication parity check setting , 0 : NO 0.2 N0 39 Red ADD Communication ADD 1.2247 1 40 REC Communication data transport sequence 000; sequence exchange; 3rd bit function reserved. sequence exchange; 3rd bit function reserved. Setting parameter reserve position: 0 (EEP): Protocol note 3 0 41 PrS EEPROM with power failure protection; 1(RAM): RAM without power failure protection; EEP/RAM EEP 43 8UE BLT No Setting time, time's up, it turns off. Unit:M EEP/RAM EEP 44 CRE CAE CAE User self-calibration enable function, this parameter is only for the input signals except N: don't use the self-calibration parameters. N: don't use the self-calibration and the signal input calibration is completed. VES/OK YES/OK 46 CRE CAE Self-calibration high limit input operation, after adding the high end signal to the signal input c	36	95	PT		0~9999	0
38 Press PR10 0: NO 1: ODD 2: EVEN 0.22 NO 39 84a ADD Communication ADD 1.247 1 40 at: 0 DTC Set into communication data transport sequence 000; Refer to COM, protocol note 3 0 41 at bit function reserved; 2nd bit is byte sequence exchange; 3rd bit function reserved. 0 0 41 Pr5 PRS EEPROM with power failure protection; 1(RAM): RAM without power failure protection; 1(RAM): STOP reserve position; 0 (EEP): EEPROM with power failure protection; 1(RAM): commally on; other value: backlight stays on for the setting time, time's up, it turns off. Unit:M EEPRAM 43 bit: BLT Normally on; other value: backlight stays on for the self-calibration parameters. N: on' tuse the self-calibration parameters. N: don' tuse the self	37	583	BAD	2 (19.2): 19200	0~2	9.6
40 ⊕E Communication data transport sequence 000; Ist bit function reserved; 2nd bit is byte sequence exchange; 3rd bit function reserved; note ③ Refer to COM, note ③ 0 41 ₽-5 Setting parameter reserve; position: 0 (EEP): EEPROM with power failure protection; 1(RAM): RAM without power failure protection. EEP/RAM EEP 42 -55 RSS EEPROM with power failure protection; 1(RAM): RAM without power failure protection; 1(RAM): RAM without power failure protection. EEP/RAM EEP 43 645 BLT normally on; other value: backlight stays on for the setting time,time's up,it turns off. Unit:M 0 ~ 10 5 44 CRE CAE CAE User self-calibration enable function, this parameter is only for the input signals except TC/RTD; Y:enable the self-calibration parameters. 0 (N) N N 45 CRE Self-calibration low limit input operation, after adding the low end signal to the signal input calibration is completed. YES/OK YES 46 CRH CAH terminal, flash YES to activate, after confirm and display OK, the input signal to the signal input calibration is completed. YES/OK YES 47 'YEr VER Software version. — —	38	ዖራሪዓ	PRTY	0 : NO 1 : ODD 2 : EVEN	0~2	N0
40 Set DTC 1st bit function reserved; 2nd bit is byte notecol note ③ 0 41 Setting parameter reserve position: 0 (EEP): 1(RAM): RAM without power failure protection; 1(RAM): STOP reserve position:): 0 (EEP): EEPROM with power failure protection; 1(RAM): setting; 0: backlight stays normally on; other value: backlight stays on for the setting time setting; 0: backlight stays on for the setficalibration parameters. Normally on; other value: backlight stays on true self-calibration parameters. N: don't use the self-calibration parameter. Self-calibration is completed. 0 (N) N 46 CAL CAL terminal, flash YES to activate, after confirm and display OK, the input signal low end calibration is completed. YES/OK YES 47 VER VER Software version. — —	39	868	ADD			1
41 PrS Setting parameter reserve position: 0 (EEP): EEPROM with power failure protection; 1((RAM): RAM without power failure protection. EEP/RAM EEP 42 -55 RSS EEPROM with power failure protection; 1((RAM): RAM without power failure protection; 1(RAM): RAM without power failure protection. EEP/RAM EEP 42 -55 RSS EEPROM with power failure protection; 1(RAM): RAM without power failure protection. EEP/RAM EEP 43 645 BLT mormally on; other value: backlight stays on for the setting time,time's up,it turns off. Unit:M 0 ~ 10 5 44 CRE CAE User self-calibration enable function, this parameter is only for the input signals except 0 (N) N: don' t use the self-calibration parameters. 0 (N) N: don' t use the self-calibration parameters. N: don' t use the self-calibration parameters. 45 CRE Self-calibration low limit input operation, after adding the low end signal to the signal input calibration is completed. YES/OK YES 46 CRE CAH Self-calibration high limit input operation, after adding the high end signal to the signal input calibration is completed. YES/OK YES 47 VER VER Software version. — —	40	366	DTC	1st bit function reserved; 2nd bit is byte sequence exchange; 3rd bit function reserved.	protocol	0
42 -SS RSS EEPROM with power failure protection; 1(RAM): RAM without power failure protection. EEP/RAM EEP 43 bL Backlight delay time setting, 0: backlight stays normally on; other value: backlight stays on for the setting time, time's up, it turns off. Unit:M 0~10 5 44 CRE CAE parameter is only for the input signals except N: don't use the self-calibration parameters. N: don't use the self-calibration parameters. 0 (N) 1 (Y) N 45 CRI CAE Self-calibration on ble function, this parameter is only for the input signals except N: don't use the self-calibration parameters. N: don't use the self-calibration parameters. 0 (N) 1 (Y) N 45 CRI CAE Self-calibration low limit input operation, after adding the low end signal to the signal input calibration is completed. YES/OK YES 46 CRH CAH terminal, flash YES to activate, after confirm and display OK, the input signal to the signal input calibration is completed. YES/OK YES 47 'VEr VER Software version. — —	41	P~S	PRS	EEPROM with power failure protection; 1(RAM): RAM without power failure protection.	EEP/RAM	EEP
43 BLT normally on; other value: backlight stays on for the setting time,time's up,it turns off. Unit:M 0~10 5 44 CRE CAE resting time,time's up,it turns off. Unit:M 0 (N) N 44 CRE CAE resting time,time's up,it turns off. Unit:M 0 (N) N 44 CRE CAE resting time,time's up,it turns off. Unit:M 0 (N) N 44 CRE CAE resting time,time's up,it turns off. Unit:M 0 (N) N 44 CRE CAE resting time,time's up,it turns off. 0 (N) N 45 CRE Self-calibration low limit input operation, after adding the low end signal to the signal input calibration is completed. YES/OK YES 46 CRH CAH terminal, flash YES to activate, after confirm and display OK, the input signal to the signal input calibration is completed. YES/OK YES 47 YEr VER Software version. — —	42	-55	RSS	EEPROM with power failure protection; 1(RAM): RAM without power failure protection.	EEP/RAM	EEP
44 CRE CAE parameter is only for the input signals except TC/RTD; Y:enable the self-calibration parameters. N: don't use the self-calibration parameters. 0 (N) 1 (Y) N 45 CRL Self-calibration low limit input operation, after adding the low end signal to the signal input calibration is completed. VES/OK YES 46 CRH CAL terminal, flash YES to activate, after confirm and display OK, the input signal low end calibration is completed. YES/OK YES 46 CRH CAH terminal, flash YES to activate, after confirm and display OK, the input signal high end calibration is completed. YES/OK YES 47 YEr VER Software version. — —	43	6U:	BLT	normally on; other value: backlight stays on for the setting time,time's up,it turns off. Unit:M	0~10	5
45 CRL adding the low end signal to the signal input terminal, flash YES to activate, after confirm and display OK, the input signal low end calibration is completed. YES/OK YES 46 CRH CAL terminal, flash YES to activate, after confirm adding the high end signal to the signal input calibration high end signal to the signal input and display OK, the input signal high end calibration is completed. YES/OK YES/OK 47 'YEr VER Software version.	44	CRE	CAE	parameter is only for the input signals except TC/RTD; Y:enable the self-calibration parameters;		Ν
46 CRH adding the high end signal to the signal input terminal, flash YES to activate, after confirm and display OK, the input signal high end calibration is completed. YES/OK YES 47 YEr VER Software version. —— ——	45	C 8L	CAL	Self-calibration low limit input operation, after adding the low end signal to the signal input terminal, flash YES to activate, after confirm and display OK, the input signal low end calibration is completed.	YES/OK	YES
		-		adding the high end signal to the signal input terminal, flash YES to activate, after confirm and display OK, the input signal high end calibration is completed.	YES/OK	YES
	47	1987	VER	Software version. 5		

	larm parameters and o bol description: "☆" me	output logic diagram: eans HY, "▲" means alarm value, "∆" means SV value
No.	Alarm mode	Alarm output (AL1&AL2 are independent from each) Image:the hatched section means the alarm action
1	High limit absolute value alarm	
2	Low limit absolute value alarm	AL SV
3	∺High limit deviation value alarm	→ → PV
4	XLow limit deviation value alarm	SV-AL SV
5	%High/low limit deviation value alarm	SV-AL SV SV-AL
6		→ ☆ ☆ → PV sv-aL sv sv-aL
No.	Alarm mode	The below two alarm parameters(AL1,AL2) are used in combination, AL1 alarm output, AD2 must be set as 0
7	High and low limit absolute value interval alarm	$\begin{array}{c c} & & & & & \\ \hline & & & & & \\ \hline & & & & \\ \hline & & & &$
8	※High and low limit deviation value interval alarm	→☆↓ ☆↓ → PV sv-AL1 Sv sv+AL2
9	High limit absolute value and low limit deviation value interval alarm	Image: sy-All All PV
10	※High limit deviation value and low limit absolute value interval alarm	ALL SV SV+AL2 PV
11	High/low limit absolute value alarm	

ation value alarm When the alarm value with deviation alarm is set as a negative number, it will be dealed as an absolute value.

→ → P\

(2) Alarm extension function table

value alarm %High/low limit devi-

12

	CALCH		
AE1/AE2 value		Alarm handling method when it displays HHHH/LLLL	Remark
Power on, alarm	0	The alarm remains the state 1 second before it displays HHHH/LLLL	As long as the alarm
does not	1	Forced alarm output	condition is met, alarm
inhibit	t 2 Forced alarm close		will output.
Power on,	3	The alarm remains the state 1 second before it displays HHHH/LLLL	Before the PV value reaches the SV for the
alarm inhibit	4	Forced alarm output	first time, the alarm will
minion	5	Forced alarm close	not output

IX. Key function operation

1. Monitoring mode operation (RUN/STOP)

- 1) Under the measure mode, long press" a" to enter the monitoring mode, and it will display "STOP" on the SV window. Long press " a" to exit.
- 2) It can modify SV value and switch operation mode even displaying STP.
- Under the monitoring mode, main control output will stop or set min output except alarm output and analog output.

2. PID parameter identification and auto-tune operation:

The factory default PID parameters usually does not apply to usage occasion; please use auto-tuning function to get a suitable PID parameter.

- 2) The meter will enter control output since power on, so please set the monitoring mode to avoid any influence on the auto-tune effect, or switch off the power of control output load. No matter how it operates, should guarantee the set value greater than the current measured value, and the bigger the drop is, the better it will be.
- 3) In order to avoid the influence caused by alarm interlocking output, please set the proper alarm value in advance, or exclude the alarm influence.
- 4) Set PID type and SV value; the factory default setting is fuzzy PID.
- 4) Set FID type and SV value, the factory default setting is fuzzy field.
 5) Set as PID control, if there is OLL & OLH output limiting, please set the output to a proper range; factory default setting is OLL=0%, OLH=100%.
 6) Under the condition that PV value is at normal room temperature, please exit monitoring mode or power on the load, and long press " « " to enter auto-tune mode, then, AT indicator is on.
- 7) Auto-tune will take some time, in order not to affect auto-tune result, please don't modify the parameters or power-off.
- 8) When AT light goes out, it automatically exits auto-tune mode, PID parameters will be updated automatically, at that time, it will auto control exactly.
 9) It will stop the auto-tune if long press "«" key, measure beyond the scope, display abnormally, swith to "STOP" mode, or power-off in the process of auto-tune.
- 10) Note: In the occasions with output limiting operation, sometimes, even if the auto-tune is carried out, the best PID parameters still cannot be obtained. 11) Experienced users can set a proper PID parameter according to their experience.

3.PID & Cooling control operation

1) PID control acts on mail control output OUT1, cooling control acts on OUT2. 2) AL1 alarm and OUT2 are multiplex function, when using the cooling control, please set AD1 as 0; the 1st alarm function will not work after setting.
3) Please set the control mode OT as 3.

c) Please set the cooling start hystersis DB to a value greater than 5, to ensure the cooling would not affect the PID control.

5) Please change the cooling control cycle CP1 to a proper value, and change the cooling proportionality coefficient to a a proper value.
6) When PV value > SV+DB value, the cooling control start to effect; the bigger value of PV, the longer output time of OUT2
4. Auto-manual switch function

1) Enter common manual, set parameter A-M as "AM". 2) After return back to measure control interface, press SET key to switch auto-manual operation. 6

- 3) When it is switched to manual control, lower line LED will display output percentage: M0~M100 (corresponding to 0%~100%), press Add Key or Reduce Key to modify the output percentage.
 4) Before the manual control is switched to auto control, press Left Key to modify
- the SV value, so as to switch the control mode smoothly. 5) After the meter is rebooted, the default setting is manual control and output 0.
- 5. Fix manual control function

 - 2) Set A-M parameter as "MAN".
 2) After return back to measure control interface, user can modify output
 - percentage by manual.
 - 3) After the meter is powered on again, the manual output percentage can be restored.
- 6. Linear signal self calibration function operation
 - 1) Set up the INP type, and ensure it is one of these input 0 ~ 50mV, RT(0 ~ 400 Ω), 4 ~ 20mA and 0 ~ 10V.

 - 2) Add the input signal to the correct input channel.
 2) Add the input signal to the correct input channel.
 3) Enter menu low-limit calibration CAL menu, press "[《]" to flash"YES"; and set the input signal to minimum value and input it to the meter.
 4) When "YES" is flashing, and the minimum value of the signal has been input to the meter, please press "SET" to ensure and save the calibrating value.
 5) After additional to the input signal to the input signal to the input signal to the input signal to ensure and save the calibrating value. 5) After calibrating low-limit, enter the high-limit calibration CAH menu, and flash
 - YES

 - 6) Set the input signal to maximum value and input it into the meter, and press "SET" to ensure and save the calibrating value when the "YES" is flashing.
 7) After calibrating, enter CAE menu, change "N" to "Y" to enable the calibrating value; otherwise, it still use the factory default value.
 9) The linear signal value when the input deput due to wood the input standard to an another the standard to an an an an an an an another the standard to an a
 - 8) The linear signal value of high-limit input should not exceed the input standard value range ±10%.
 - 9) If not satisfied with the calibrating result, could calibrate again.

X. Methods of simple fault

Display	Checking method
LLLL/HHHH	Check the wire connection, FH and FL value, working environment temperature and whether input signal is selected correctly.

XI. Communication procotol

Meter use Modbus RTU to do RS485 half-duplex communication.Reading function code 0x03, writing function code 0x10 / 0x06. The meter use 16digits CRC to check and will not feedback any information of checked error.

Data frame format:								
Start bit	Data bit	Stop bit	Check bit					
1	8	1	Setting in Menu PRTY					

Handling of abnormal communication: If there is abnormal response, put 1 on the highest bit of function code. For example: Host request function code is 0x03, and the response function code from guest should be 0x83. Error code:

0x01—Illegal function: the function code sent from host is not support by meter. 0x02—Illegal address: the register address designated by host beyond the

address range of meter. 0x03—Illegal data: the writing data sent from host beyond the writing range of meter. Communication cycle: Communication cycle is the time from host request to client back to data:

communication cycle=time of request+time of guest response+time of response delay+time of response returning. Take 9600 baud rate as example: The communication cycle of single measure data is not less than 250ms.

Communication cycle of single measure data is not less than 250ms. 1. Read register For example:Host reads integer SV(set value 200) The ADD code of SV is 0x2000, because SV is integer(2 dyte), seizes 1 data register. The memory code of decimal integer 200 is 0x00C8 Note:It should read DP value or ensure DP value in first to ensure the decimal point when reading data, and need to transform the reading data to get the actual value. Conversely, it should transform the data to corresponding ratio before writing the data in meter.

before writing the data in meter. Host request (Read multi-register)

1	2	3	4		5	56		5 7			8
Meter ADD	Function code	Start ADD High bit	Start ADD Low bit		Data Leng high		Data byte Length low bit		code		<pre>%CRC code nigh bit</pre>
0x01	0x03	0x20	0x0	00	0x	00	0>	:01	0x8F		0xCA
		Gue	st nor	mal a	answe	er(Rea	d mu	lti-regi:	ster)		
1	2	3			4		5		6		7
Meter ADD	Function code	Data byte number					ata XCR w bit low b		C code it		CRC code gh bit
0x01 0x03 0x02			0x	0x00 0xC		C8 0>		:B9		0xD2	
Function	Function code abnormal answer: For example: host request ADD is 0x2011)										
	Cuest sharmed ensurer(Dead multi register)										

Guest abnormal answer(Read multi-register)									
1	2	3	4	5					

Meter ADD	Function code	Error code	CRC code	%CRC code high bit
0x01	0x83	0x02	0xC0	0xF1

2、Write multi-register

Meter

ADD

0x01

ADD

High bit

0x20

Functior

0x06

code

For example:Host write SV with 0x10 function setting value 150 ADD code of SV is 0x2000,because SV is integer(2 dyte),seizes 1 data register. The hexadecimal memory code of decimal integer 150 is 0x0096.

ADD

0x00

Low bit

	Host request (write multi-register)													
1	2	3	4		5		6		7	8	9	1	.0	11
Meter ADD	Function code	Start ADD High bit	Star ADE Low)	Length		te Data byt Length Iow bit		Data byte Length	Data high bit	Data 🔆 low cor bit lov		de	%CRC code high bit
0x01	0x10	0x20	0x0	00x00 0x00			0x01		0x02	0x00	0x96	0>	:07	0xFC
	Guest normal answer (write multi-register)													
1 2 3 4 5 6 7 8										8				
Mete ADD	Meter Function Start ADD St ADD code High bit Lo						ata byte ength igh bit	Data byte Length low bit		×CI	XCRC code		XCRC code high bit	
0x01 0x10 0x20				0x00 0x00		0x01	0x0A		0x09					
Host w	Host write SV with 0x06 function (setting value 150)													
	Host request (write single-register)													

Data

high bit

0x00

Data

low bit

0x96

low bit

0x02

			(Guest norm	al answer	(write sin	gle-r	egister)				
1		2	3	4	5	6	Ĭ	7	8			
Met	ter Fund	ction	ADD	ADD	Data	Data	жс	RC code	XCRC code			
ADI	D code	•	High bit	Low bit	high bit	low bit	low	bit	high bit			
	0x01 0x06 0x20 0x00 0x00 0x96						0x02 0x64					
Data location error response: (For example:Host request the ADD index is 0x200F)												
			Gues	t abnorma	l answer (write mult	i-reg	gister)				
	1	1	2	3		4			5			
Meter ADD Function code Error code XCRC code low bit XCRC code												
	0x01		90	0x02		0xCD			0xC1			
	· · ·			leter Para								
	Add(Regis			Variable	name			ister R/W				
1				value SV			1	R/W				
2	0x2001	(4819	4) 1st I	oop alarm	value AL1	1.15.7.4	1	R/W				
3				oop alarm			1	R/W	_			
4				loop alarm			1	R/W				
5			- /	loop alarm		s HY2	1	R/W				
6				lay low lim			1	R/W				
7				lay high lir			1	R/W				
8			- 1	og output			1	R/W	-			
9				og output	-		1	R/W	Default 1			
10	0x2009(4820	2) Con	trol output	Iow limit C		1	R/W	decimal poin			
11	0x200A(4820	3) Con	trol output	high limit	OLH	1	R/W	Default 1 decimal poin			
12				rshoot limi	•		1	R/W				
13	,		-4	& Cool co		ZODO DP		R/W				
	0.2000	4020			ntroi dead	Zone DB			Default 1			
14	0x200D(4820	6) Prop	ortional coe	efficient of a	cooling PC	1	R/W	decimal			
15	0x200E(4820	7) Tran	slation co	rect PS		1	R/W	point			
			-1				1		Engineering			
16	0x200F(48208) Dispaly fuzzy tracking value DTR							R	work without decimal poir			
17	0x2010(48209) Measure value PV							R	uecima poin			
18			-	out percen			1	R/W	0~100			
									O. A.uto.			
19		-	,	-Manual s			1	R/W	1: Manual			
20	0x2013(4821	2) Settir	ng paramete	r reserve po	sition PRS	1	R/W	'			
21				I/STOP Re				R/W				
22	0x2015(4821	4) Back	dight delay	/ time BLT		1	R/W				
			R	eserve								
23	0x2100(48449) 1st loop alarm type AD1						1	R/W	·			
24	0x2101(4845	0) 2nd	loop alarm	type AD2		1	R/W				
25	0x2102(4845	1) 1st lo	oop alarm e	extended n	node AE1	1	R/W				
26	0x2103(oop alarm	extended i	node AE2	1	R/W	·			
27	0x2104(4845	3) Con	trol type O	Т		1	R/W				
28	0x2105(4845	4) Outp	out type AC	СТ		1	R/W				
	0.0105	40.15							1:RUN 2:STF			
29	Ux2106(4845	5 RUN	I STOP op	eration		1	R/W	3:Run auto-tune 4:Stop auto-tune			
30	0x2107	(4845)	6) Deci	mal point	DP		1	R/W				
31				display U⊺			1	R/W	25/0C) 26/0E			
32			·	r constants			1	R/W				
32 33				ortional co)	1	R/W	-			
33 34				gral time I	enicient P		1	R/W				
					- D		1		-			
35	0x210C		- 1	rential tim		חסי	1	R/W				
36	0x210D						1	R/W				
37 38		0x210E (48463) Heating control cycle CP					1	R/W				
30		0x210F (48464) Cooling control cycle CP1 0x2110 (48465) Cooling relay time PT					1	R/W				
39							1	R/W	· · ·			
39 40	0x2111 (48466) Optional input signal INP 0x2112 (48467) Meter address ADD						1	R/W	-			
_	0x2112	0x2113 (48468) Communication baud rate BAD					1	R				
40		48468	3) <u> </u> Com	0x2114 (48469) Communication delay setting DTC								
40 41	0x2113		9) Com						Note 3			
40 41 42 43 44	0x2113 0x2114 0x2115	(48469 (4847)	9) Com 0) PID	arithmetic			1	R				
40 41 42 43 44 45	0x2113 0x2114 0x2115 0x2116	(48469 (48470 (4847	9)Com))PID 1)Lock	arithmetic key LCK			1	R				
40 41 42 43 44 45 46	0x2113 0x2114 0x2115 0x2115 0x2116 0x2117	(48469 (4847) (4847 (4847)	9) Com 0) PID 1) Lock 2) Mete	arithmetic key LCK er name			1	R R				
40 41 42 43 44 45	0x2113 0x2114 0x2115 0x2116 0x2116 0x2117 0x2118	(48469 (4847) (4847) (4847) (4847)	9) Com 0) PID 1) Lock 2) Mete 3) Outp	arithmetic key LCK er name	type PDC		1	R	Note ②			

Note 0: the register humber is the address converted to decimal plus 1 and then the register identification code 4 is added in front; for example: the register number of the data address 0x2000 is 8192 + 1 = 8193 and then 4 is added in front, that is, the register number 48193; Related applications can be seen, such as Siemens S7-200 PLC. Note 0: Measurement status indication. When the data bit is 1, it means execution, and when it is 0, it means no execution.

D7	D6	D5	D4	D3	D2	D1	D0			
STOP	НННН	LLLL	AT	AL2	AL1	OUT2	OUT1			
Note③: DTC communication data transmission sequence and response delay description										

Note(3). DTC comminutation data transmission sequence and respected to a commission sequence an

unsigned int Get_CRC(uchar *pBuf, uchar num)

unsigned i,j; unsigned int wCrc = 0xFFFF; for(i=0; i<num; i++)

wCrc ^ = (unsigned int)(pBuf[i]); for(j=0; j<8; j++)

if(wCrc & 1){wCrc >> = 1; wCrc ^ = 0xA001; }

8

wCrc >>= 1:

return wCrc:

}

%CRC code %CRC code

high bit

0x64