✓ TOKY[®] 广东东崎电气有限公司 东崎仪表 TOKY electrical co.,ltd.

Intelligent Temperature Controller

For GTP-A Version

http://www.toky.com.cn



Features:

⊙Multi input signal, multi models for option

- ⊙ With measurement display, control output, alarm output, transmission output, RS485 communication, etc
- ⊙ Multi PID control algorithms for option, with self-turning function.
- Suitable for industrial machinery, machine tools, general measuring instruments and equipments.

National High-tech Enterprise / National Stan	۲	٢	٢	GB	(18) (18)	Þ	
O-miss lines 400.0700.400) (and an and a	KKOTE				0.40	04.4
Service line: 400-0760-168	Version code:	KKGIP	-A01	E-A/	0-20	240	614

This manual describes the settings, wiring, and names of various parts of the thermostat. Please read this manual carefully before using this product, and use it correctly after understanding the content. And please keep it in a safe place for future reference.

I. Precautions for safety use

A Warnning

- 1) When a malfunction or abnormality of this product may cause a serious accident in the system, please install an appropriate protection circuit externally.
 2) Do not turn on the power until all wiring is completed. Failure to do so may cause electric shock, fire, or malfunction.
 3) Do not use outside the scope of the product specifications. Doing so may cause fire or failure.
 4) Do not use in places with flammable or explosive gas.
 5) Do not touch high-voltage parts such as power terminals after power-on. Otherwise there is a danger of electric shock.

electric shock Do not disassemble, repair and modify this product. Failure to do so may cause electric shock, fire, or malfunction.

Caution

- This product must not be used in atomic energy equipment and medical equipment related to human life.
 When this product is used in a domestic environment, radio wave interference may occur. Adequate countermeasures should be taken at this time.
- 3) This product is protected against electric shock through reinforced insulation. When embedding this product
- in a device and wiring, follow the specifications that the embedded device meets.
 In order to prevent the occurrence of surge when all indoor wiring is longer than 30m when this product is used and in case the wiring is outdoor, an appropriate surge suppression circuit must be installed.
 This product is manufactured on the premise that it is installed in a cabinet. In order to prevent users from
- approaching high-voltage parts such as power terminals, please take necessary measures on the final
- approaching inger binger bing accident.
- accurate.
 7) Please observe local regulations when wiring.
 8) In order to prevent damage to the machine and prevent machine failure, please install an appropriate capacity fuse on the power cord or larger capacity input and output lines connected to this product to
 protect the circuit.
- Please do not mix metal pieces and wire debris into this product, otherwise it may cause electric shock, fire and failure. 10) Tighten the screws with the specified torque. Failure to fully tighten the screws may result in electric shock
- or fire. 11) In order not to hinder the heat dissipation of this product, please do not block the heat dissipation window
- holes not connect any wires to the unused terminals of this product.
 12) Do not connect any wires to the unused terminals of this product.
 13) Be sure to clean it after the power is off. Wipe the dirt on the product with a dry soft cloth, and do not use
- hygroscopic agents, otherwise it may cause deformation and discoloration. 14) Please do not hit or wipe the display panel with hard objects. 15) This manual assumes that the reader has basic knowledge in electrical, control, computer, and
- communications.
- 16) The illustrations, data examples, and screen examples used in this manual are entered for easy understanding of the manual and are not guaranteed to be the result of their operation. 17) In order to use this product safely for a long time, regular maintenance is necessary. Some parts of this
- 18) without are limited by lifespan, and some may change due to long-term use.18) Without prior notice, the contents of the manual may be changed. The content of the manual is expected to be free of any loopholes. If you have any questions or objections, please contact us.

A Installation and wiring precautions

- This product is used in the following environmental standards. (IEC61010-1) [Overvoltage Category II, 1)
- Pollution Degree 21
 Please use within the surrounding environment, temperature, humidity and environmental conditions of the following : Temperature: 0 to 50 ° C; Humidity: 45 to 85% RH; Environmental conditions: indoor use, altitude less than 2000m.

3) Avoid using in the following places: places where condensation may occur due to drastic temperature 6) Avid using in the following places, places where concernsation may occur due to track the interaction of the following places, here correstive gas or flammable gas is generated; places where direct vibration or may impact the product; water, oil, chemical Products, smoke, Places with steam, places with a lot of dust, salt, and metal powder, places with large clutter interference, and prone to static electricity, magnetic fields, and noise; places where the airflow of air conditioning or heating directly blows; places with direct sunlight; Places where the airflow of air conditioning or heating directly blows; places with direct sunlight; Places where heat can build up.

- 4) For installation, please consider the following points before installation: In order not to saturate the heat, allow sufficient ventilation space
- In order not to saturate the heat, allow sufficient vehilation space. Please consider the wiring and maintenance environment, etc. Please make sure that there is more than 50mm space above and below this product. Please do not install it directly above the heat-generating machine (such as heater, transformer, semiconductor manipulator, high-capacity resistor). If the ambient temperature is above 50 ° C, use a forced fan or cooler to cool it. However, do not allow the cooled air to blow directly into the product. In order to improve anti-interference performance and safety, please install as far away as possible from bidh voltare equipment and nower equipment
- from high-voltage equipment and power equipment. Tom high-voltage equipment and power equipment. Do not install high-voltage machines in the same cabinet as this product. The distance between this product and the power line should be more than 200mm. Install the power machine as far away as possible.

 \triangle

Wiring precautions:

- In the case of thermocouple input, please use the specified compensation wire; if the device to be measured is a metal heating object, please use insulated thermocouple; the thermocouples must be isolated from each other.
 In the case of thermal resistance input, please use a wire with a small resistance and a (3-wire) non-resistance difference, but the total length should be within 5m; this product does not have this foreithe of the time better.
- function for the time being. 3) In order to avoid the influence of noise interference, please keep the input wire away from the instrument
- 3) In order to avoid the influence of noise interference, please keep the input wire away from the instrument power line, power supply line and load line.
 4) In order to reduce the influence of power and heavy load power lines on this product, it is recommended to use a noise filter where it is easily affected. If using a noise filter, be sure to install it on a grounded panel and minimize the wiring between the output side of the noise filter and the power terminals; do not install fuses, switches, etc. on the wiring of the output side of the noise filter. Otherwise, the effect of the output line and the power terminals; do not install fuses. the filter will be reduced.
- the filter will be reduced.
 5) The output time of this product when it is powered on is about 5 seconds. If signals such as interlocked circuits are used, please use a delay relay.
 6) Please use shielded twisted pair as far as possible for the transmission output line. If necessary, you can also connect a common mode coil at the front of the signal receiving equipment to suppress the interference of the line and ensure the signal is reliable and stable.
 7) Please use shielded twisted-pair cables for long-distance RS485 communication lines, and ground the shielding layer on the host side to ensure reliable and stable communication.
 8) There is no fuse for this product; please configure it according to the rated voltage 250V and rated current 14. fuse torce.
- current 1A, fuse type: time-delay fuse. 9) Please use a suitable "Slotted" screwdriver and wire,

Trense use a suitable soluted screwdiver and wire, Terminal pitch: 5.0mm Screwdriver size: 0.6X3.5 "Slotted" length is more than 130mm Recommended tightening torque: 0.5N.m Suitable wire: 0.25 to 1.65mm single or multi-core flexible cord 10) Do not contact the crimp terminal or the bare wire with an adjacent terminal.

_Terminal dimer

6.8mm max \bigcirc 6 8mm max 3.5mm min Φ3.5mm min

11) The temperature resistance of the wire connected to the terminalshould be at least 70°C.

II. Model Illustration



III. General model description

		OUT1 control output			Alarm output			Analog	Comm.	Auxiliary power
No.	Model number	RELAY	SSR	4~20mA	AL1 OUT2	AL2	AL3	4 ~ 20mA	RS485	24V
1	GTP□-MC18□	•	•		•	•			•	•
2	GTP□-MC10□	•	٠		•	•				•
3	GTP□-IMC18□	•	•	•	•	٠		0	•	•
4	GTP□-IMC10□	•	٠	•	•	•		0		•

 \Box :The default "Blank" input signal is TC/RTD/Mv/Rt; "X" input signal is 4 \sim 20mA/0 \sim 10V. Standard configuration function.

SWith this function, but multiplexed with other functions. This series has only one DC 4-20mA output, but it can be configured for main control output or transmission output through the ACT menu

IV Main Technical Parameters

Sampling speed	2 times per second
Relay capacity	AC 250V /3A Life of rated load>100000 times
Power supply	AC/DC 100 ~ 240V (85-265V), DC 24V
Total consumption	< 10VA
SSR output	DC 24V impulse level, load<30mA
Current output	DC 4~20mA load<500Ω
Communication port	RS485 port Modbus-RTU protocol
Insulation impedance	Input, output, power to housing>20MΩ
ESD	IEC/EN61000-4-2 Contact ±4KV /Air ±8KV perf.Criteria B
Pulse traip anti-interference	IEC/EN61000-4-4 ±2KV perf.Criteria B
Surge immunity	IEC/EN61000-4-5 ±2KV perf.Criteria B
Voltage drop & short interruption immunity	IEC/EN61000-4-29 0% ~ 70% perf.Criteria B
Isolation withstand voltage	Signal input & output & power 3000VAC 1min, <60V Low voltage circuit between DC500V,1min
Power-off protection	10 years,times of writing:1 million times
Panel protection level	IP65(IEC60529)
Safety standard	IEC61010-1 Overvoltage category II, pollution level 2, level II (Enhanced insulation)
Shell material	PC/ABS (flame class UL94V-0)
Panel material	PC
Weight	About 300g
Ambient environment	Indoor use, temperature: 0~50°C, no condensation, humidity:<85%RH, altitude<2000m

3	Measurement	signal	parameter table	

3. Measurement signal parameter table								
Input type	Symbol	Measurem ℃	ent Range °F	Resolution	Accuracy (23°C±0.5)	Input resistance Auxiliary current	Commincatio Code	
K1	51	-50 ~ 1200	$-60 \sim 2200$	1°C	0.5%F.S±3digits	>1MΩ	0	
K2	85	$-50.0 \sim 999.9$	$-60.0 \sim 999.9$	0.2°C	0.5%F.S±1°C	>1MΩ	16	
J1	ا ل	$0 \sim 1200$	$0 \sim 2200$	1°C	0.5%F.S±3digits	>1MΩ	1	
J2	SL	$0.0\sim999.9$	$0 \sim 999.9$	0.2°C	0.5%F.S±1°C	>1MΩ	17	
E1	E١	$0 \sim 850$	$0 \sim 1500$	1℃	0.5%F.S±3digits	>1MΩ	2	
E2	53	$0.0 \sim 850.0$	$0 \sim 999.9$	0.3°C	0.5%F.S±1°C	>1MΩ	18	
T1	٤l	$-50 \sim 400$	$-60 \sim 750$	1℃	0.5%F.S±3°C	>1MΩ	3	
T2	F5	$-50.0 \sim 400.0$	$-60.0 \sim 750.0$	0.4°C	0.5%F.S±3°C	>1MΩ	19	
В	Ь	$250 \sim 1800$	$250 \sim 3200$	1℃	1%F.S±2°C	>1MΩ	4	
R	г	-10 ~ 1700	$-10 \sim 3000$	1℃	1%F.S±2℃	>1MΩ	5	
S	5	-10 ~ 1600	-10 ~ 2900	1℃	1%F.S±2℃	>1MΩ	6	
N1	- 1	-50 ~ 1200	$-60 \sim 2200$	1°C	0.5%F.S±1°C	>1MΩ	7	
N2	-2	$-50.0 \sim 999.9$	$-60 \sim 999.9$	0.2°C	0.5%F.S±1°C	>1MΩ	20	
PT100-1	PE1	$-200.0 \sim 600.0$	$-200.0 \sim 999.9$	0.2°C	0.5%F.S±0.3°C	0.33mA	8	
PT100-2	PF5	$-200 \sim 600$	$-300 \sim 1100$	1°C	0.5%F.S±3digits	0.33mA	21	
JPT100-1	19E1	$-200.0 \sim 500.0$	$-200.0 \sim 900.0$	0.2°C	0.5%F.S±0.3°C	0.33mA	9	
JPT100-2	76F5	$-200 \sim 500$	$-300 \sim 900$	1°C	0.5%F.S±3digits	0.33mA	22	
CU50-1	CUSI	$-50.0 \sim 150.0$	$-60.0 \sim 300.0$	0.2°C	0.5%F.S±3°C	0.33mA	10	
CU50-2	CUS2	$-50 \sim 150$	$-60 \sim 300$	1°C	0.5%F.S±3°C	0.33mA	23	
CU100-1	CU01	-50.0 ~ 150.0	$-60.0 \sim 300.0$	0.2°C	0.5%F.S±1°C	0.33mA	11	
CU100-2	2003	$-50 \sim 150$	$-60 \sim 300$	1℃	0.5%F.S±3digits	0.33mA	24	
$0\sim 50mV$	50 50	-1999	~ 9999	12bit	0.5%F.S±3digits	0.33mA	12	
$0\sim 400\Omega$	r۲	-1999	~ 9999	12bit	0.5%F.S±3digits	0.33mA	13	
* 4 ~ 20mA	ō8	-1999	\sim 9999	12bit	0.5%F.S±3digits	<50Ω	14	
$*~0 \sim 10V$	2	-1999	~ 9999	12bit	0.5%F.S±3digits	>1MΩ	15	

*: Please indicate the input signal requirements before order.

3、隔离模式框图:



Reinforced insulation, isolation voltage AC3000V
Functional insulation, isolation
voltage AC500V

V. Dimensions and installation method.

1、Dimensions and hole size.



VI. Connection Diagram



In case of any change, please subject to the wiring diagram on the actual equipment.

VII. Name of universal panel



No.	Symbol	Name	Function description
	OUT1	OUT1 LED(orange)	Main control output indicator, light when the output is ON
	OUT2	OUT2 LED(orange)	Cooling output indicator, light when the output is ON
1	AL1	Alarm1# LED(orange)	1st alarm output indicator: ON=Alarm output, OFF=no output.
	AL2 Alarm2 # LED(orange)		2nd alarm output indicator: ON=Alarm output, OFF=no output.
	AT AT LED (orange)		Self-tuning indicator, when it lights up, it is in the tuning state
2	SET	SET function key	Menu key/confirm key, used to enter or exit parameter modification mode or confirm saving modified parameters
3	«	Shift/AT Key	Activation key/shift key/AT auto-tuning key, long press to enter or exit auto-tuning in measurement control mode
4	*	Increase /R/S	Increase key. In measurement control mode, press and hold to switch between RUN/STOP mode and view the menu in reverse order.
5	*	Decrease Key	Decrease key, view menu in normal order
6	SV	Display window(Green)	Setting value or parameter display window, "STOP" means control is stopped.
7	PV	Display window(White)	Measurement value or parameter code display window

VII. Operation Process and Menu Illustration

1. Operation process and method 1) Modify the SV setting value



Short press "* key to Short press "* key to increase the SV value decrease the SV value maintain the SV value Short press" «"key and SV value flash 2).Common Menu



Long press "SET" >3 sec , enter common menu





2、Operation examples

1) Example 1, ON/OFF control:

Sensor: K type, measure range -50~1300°C; target temperature: 100°C; control mode: heatin; control requirement: ON/OFF control, when current temperature PV reaches 100°C, stop heating; when PV is lower than 98°C; start heating again; control output: relay; alarm: 1 alarm, when PV>110°C, alarm output on; when PV<105°C, alarm output off.

25 150	→ inp 	→	→ <u> </u>		AL1 _	→ HY1 -	AD1
1. Set target	2. Set menu	3. Set menu	4. Set menu	5. Set menu	6. Set menu	7. Set menu	8. Set menu
temperature	INP=pt	OT=1	OVS=5	ACT=0	AL1=5	HY1=7	AD1=3

SV=150

2) Example 2, PID control: Example 2, PID control: Sensor: PT100, measure range -200~600°C; target temperature: 150°C; control mode: heating; control requirement: PID control (note: in order to get stable temperature control, please use the auto-tuning function when the controller is powered on for the first time; if the temperature control is stable after the auto tuning, there is no need to repeat this step in the future usage.); control output: SSR; alarm: 1 alarm, when PV>SV+5°C, alarm output on, when PV<SV-2°C, alarm output off.

IX. Menu Illustration

No mater what model, what control mode it is, it will always display these parameters. No mater what model, what control mode it is, it will always users are point and the hidden of the control mode, these parameters will be hidden.

1.	Regular	Menu	

	5				
No.	Symbol	Name	Illustration	Setting range	Factory setting
1	5P-A	SP-M	Slope display value. When SPRT setting is valid, press SET key switching to this menu to view the heating speed.	FL ~ FH	
2	81_ (AL1	1st alarm value, note: the minus is dealed as absolute value when it is set as deviation alarm. Refer to (1) Alarm parameters and output logic diagram	FL ~ FH	10
3	881	HY1	1st alarm hystersis	0 ~ 1000	1
4	Rai	AD1 (1)	1st alarm mode. Note:when AL1 is used as OUT2(co- oling output), should set AD1=0(close alarm function). When AD1>6, 2nd alarm function is invalid.	0 ~ 12	3
5	815	AL2	2nd alarm value,	FL ~ FH	5
6	RRS	HY2	2nd alarm hystersis	0 ~ 1000	1
7	895	AD2 (1)	2nd alarm mode,see table (1) alarm logic diagram	0~6	4
8	863	AL3	3rd alarm value, note: the minus is dealed as absolute value when it is as a deviation value.	FL ~ FH	200
9	833	HY3	3rd alarm hystersis	0 ~ 1000	1
10	863	AD3 (1)	3rd alarm mode,see table (1) alarm logic diagram	0 ~ 6	1
11	PS	PS	Amend value, display value= actual measured value + amend value	FL ~ FH	0
12	:49	INP	Optional input signal. Note: after selecting the signal, please properly set below relevant parameters: SV,AL1,HY1,AL2,HY2,P,OVS,DB.	refer to input signal para- meters table page 3	K1

10 0.00000000000000000000000000000000000	Con	tinued				
14 N=N MAN(1): manual control only; AM(2): auto-manual switch AUTO-AM AU 15 P Proportional band, the smaller the value is, the mesponds, otherwise, it is slower. 0 ~ 9999 3 16 : I Integral time, the smaller the value is, the stronger the integral action is, otherwise, it is slower. 0 ~ 9999 1 17 od D Differential time, the greater the value is, the stronger the differential action. Set D=0 when controlling fast systems, e.g., pressure, speed; unit s 0 ~ 9999 3 18 odvershoot limit, during PID control process, when PV (measured value) > SV(set value) + OVS(overshoot limit), force to close output. The smaller this value is, the smaller the PID adjustment range is, the worse the control stability is. When set to 0, close this function. Please set the appropriate value according to the actual situation. 0 ~ 9999 0 19 CP CP1 OUT2 relay output cycle. Unit: s 4 ~ 200 2 20 CP1 OUT2 relay output cycle. Unit: s 4 ~ 200 2 21 PC DO/OFF control hystersis (positive and negative work tife same); when OT=3, it is the dead zone for cooling control lopsitive and negative work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 22 Sb DB Doling con	13	ob	от	relevant parameter: DB. 1: PID heating control, relavant parameters: P. I, D, OVS, CP, ST, SPD, PDC. 2: ON/OFF cooling control, relevant parameter DB; need to set PT when it is used for compressor control. 3:PID heating & cooling control(cooling control OUT2 will output through AL1 relay), relevant parameters: P, I, D, OVS, CP, CP1, PC, DB, ST, SPD, PDC. 4: Over temperature cooling output, relevant parameter: DB 5. PID cooling, relevant parameter:	0 ~ 5	1
15 P P faster the system responds otherwise, it is slower. 0 ~ 9999 3 16 Integral time, the smaller the value is, the stronger the integral action, unit same as PV 0 ~ 9999 1 16 Integral time, the smaller the value is, the stronger the integral action is, otherwise, it is weeker. 0 ~ 9999 1 17 e D Differential action is, otherwise, it is weeker. 0 ~ 9999 3 17 e D Overshoot limit, during PID control process, when PV (measured value) > SV(set value) + OVS(overshoot limit), force to close output. The smaller the value is, the worse the control stability is. When set to 0, close this function. Please set the appropriate value according to the actual situation. 0 ~ 9999 0 18 e.**S OVS fmaller the PID adjustment range is, the worse the control stability is. When set to 0, close this function. Please set the appropriate value according to the actual situation. 0 ~ 9999 0 19 CP CPI OUT1 control cycle. I: SSR control output, the stronger of cooling to the higher of value, the stronger of cooling to the bighter of value, the stronger of cooling to the bighter of value, the stronger of cooling to the bighter of value, the stronger of cooling to the bighter of value, the stronger of cooling 1 ~ 100 1 20 CPI CPI OUT2 relay output cycle. Unit: s 4 ~ 200 2 2 1 ~	14	8-6	A-M		AUTO~AM	AUTO
16 I stronger the integral action is, otherwise, it is weeker. When I=0, no integral action, unit: s. 0 ~ 9999 1 17 J Differential time, the greater the value is, the stronger the differential action is, otherwise, it is weeker. When D=0, no differential action. Set D=0 when controlling fast systems, e.g., pressure, speed; unit: s 0 ~ 9999 3 18 Overshoot limit, during PID control process, when PV (measured value) > SV(set value) + OVS(overshoot limit), force to close output. The smaller this value is, the smaller the PID adjustment range is, the worse the actual situation. Please set the appropriate value according to the actual situation. 0 ~ 9999 0 19 CP OUT1 control cycle, 1: SSR control output, 4-200: relay control output. Unit: s 1 ~ 200 2 20 CP1 OUT2 relay output cycle. Unit: s 4 ~ 200 2 21 PC PC higher of value, the stronger of cooling 1 ~ 100 1 22 B DB Doling control hystersis (positive and negative work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 23 LCW Lock function. 0001:SV value can' t be modified. 00-9999 0	15	ρ	Р	faster the system responds otherwise, it is slower.	0 ~ 9999	30
17 a D the differential action is otherwise, it is weeker. When D=0, no differential action. Set D=0 when controlling fast systems, e.g., pressure, speed; unit: s 0 ~ 9999 3 18 a.'.5 OV Overshoot limit, during PID control process, when PV (measured value) > SV(set value) + OVS(overshoot control stability is. When set to 0, close this function. Please set the appropriate value according to the actual situation. 0 ~ 9999 0 19 CP CP1 dout12 cells, 1: SSR control output, 4-200: relay control output. Unit: s 1 ~ 200 2 20 CP1 OUT2 relay output cycle. Unit: s 4 ~ 200 2 21 PC PO DUT2 control hystersis (positive and negative work the same); when OT=3, it is the dead zone for ON/OFF control hystersis (positive and negative work the same); when OT=3, it is the dead zone for DB cooling control (positive and negative work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 23 LCK Lock function. 0001:SV value can' t be modified. 0010: SV can be checked only, can' t be modified. 0~9999	16	;	I	stronger the integral action is, otherwise, it is	0 ~ 9999	120
18 or 5 OVS (measured value) > 5 V(set value) + OVS (overshoot limit), force to close output. The smaller this value is, control stability is. When set to 0, close this function. Please set the appropriate value according to the actual situation. 0 ~ 9999 19 CP OUT1 control cycle, 1: SSR control output. 1 ~ 200 2 20 CP1 OUT2 relay control output. Unit: s 4 ~ 200 2 21 PC PC OUT2 cooling proportionality coefficient, the higher of value, the stronger of cooling 1 ~ 100 1 22 ds DB CON/OFF control hystersis (positive and negative work the same); when OT=3, it is the dead zone for parameter according to the decimal point position. -1000~1000 9 23 LCK Lock function, 0001:SV value can' t be modified. 0010: SV can be checked only, can' t be modified. 00-9999 0~9999	17	8	D	the differential actiontion is,otherwise, it is weeker. When D=0, no differential action. Set D=0 when	0 ~ 9999	30
19 CP 4-200: relay control output. Unit: s 1 × 200 2 20 CPI OUT2 relay output cycle. Unit: s 4 ~ 200 2 21 PC PC bigher of value, the stronger of cooling 1 ~ 100 1 22 db DB Coing control hystersis (positive and negative work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 9 23 LCK LCck function. 0001:SV value can' t be modified. 0010: SV can be checked only, can' t be modified. 0~9999 0	18	oUS	ovs	[(measured value) > ŠV(set value) + OVS(overshoot limit), force to close output. The smaller this value is, the smaller the PID adjustment range is, the worse the control stability is. When set to 0, close this function. Please set the appropriate value according to the	0 ~ 9999	0
21 PC OUT2 cooling proportionality coefficient, the higher of value, the stronger of cooling 1 ~ 100 1 22 B DB ON/OFF control hystersis (positive and negative work the same); when OT=3, it is the dead zone for cooling control (positive and negative work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 23 Lock function. 0001:SV value can't be modified. 0010: SV can be checked only, can't be modified. 0010: SV can be checked menu. 0~9999	19	CP	СР	OUT1 control cycle, 1: SSR control output, 4-200: relay control output. Unit: s	1 ~ 200	20
21 PC higher of value, the stronger of cooling 1 ~ 100 1 22 35 DK/OFF control hystersis (positive and negative work the same); when OT=3, it is the dead zone for cooling control (positive and negative work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 5 23 Lock function. 0001:SV value can't be modified. 0010: SV can be checked only, can't be modified. 00-9999 0~9999 0	20	CP1	CP1	OUT2 relay output cycle. Unit: s	4 ~ 200	20
22 db DB the same); when ÓT=3, it is the dead zone for cooling control (positive and negative work differently); after change the INP setting, please change this parameter according to the decimal point position. -1000~1000 5 23 LCE Lock function. 0001:SV value can' t be modified. 0010: SV can be checked only, can' t be modified. 00-9999 0~9999	21	PC	PC	higher of value, the stronger of cooling	1 ~ 100	10
23 LCH LCK 0010: SV can be checked only, can't be modified. 0~9999 0	22	ძხ	DB	the same); when ÓT=3, it is the dead zone for cooling control (positive and negative work differently); after change the INP setting, please change this parameter according to the decimal point position.	-1000~1000	5
	23	ιce	LCK	0010: SV can be checked only, can't be modified.	0~9999	0

2. Advanced menu illustration

o ...

No.	Symbol	Name	Illustration	Setting range	Factory setting
24	9CE	ACT	Control execution mode. 0:relay or SSR control output. 1:SSR control output only. 2: 4-20mA control output, setting should comply with the selected configuration of the meter. 3: When this menu is set as 3,4-20mA is used as analog output for size 4,7 products. When this menu is set as 0 or 1, 4-20mA output is used as analog output, for size 6,9 products. 4: When individual SSR outputs, the main control relay will change to AL2 output in size 4,7 products; 5: When it is 4-20mA output, change AL2 to the main control relay in size 4 and 7 products. (Note: Instructions for ordering)	0~2 (0~5)	0
25	861	AE1 (2)	the 1st alarm extensions function, refer to alarm extension function table	0~5	0
26	882	AE2 (2)	the 2nd alarm extensions function, refer to alarm extension function table	0~5	0
27	863	AE3 (3)	the 3rd alarm extensions function, refer to alarm extension function table	0~5	0
28	dР	DP	Decimal point setting, 1 decimal at most for TC & RTD input	0~3	0
29	der	DTR	PV fuzzy tracking value, properly set this value on some occasions, it can get a more stable control display value, this value is unrelated with actual measured value. Note: after setting this value, when alarm setting value is equal to SV setting value, alarm output operation is subject to actual measured value. Set 0 to close this function.	0.0 ~ 2.0 (0~20)	1.0 (10)
30	۶٤	FT	Filter coefficient, the higher of value, the stronger of filter function	0 ~ 255	10
31	UE	UT	Temperature unit: °C: Celsius degrees. °F: Fahrenheit degrees. Note: No unit for linear signal	(25)℃ (26)°F	(25)°C
32	55A	SSM	RUN/STOP operation switch, 0: close 1: open This setting is only related to panel operations and is not related to communication	0 ~ 1	0
33	SEC	SLL	Limit the lower limit of the target setting value, SV cannot be modified beyond this range	FL~FH	
34	SUR	SLH	Limit the high limit of the target setting value, SV cannot be modified beyond this range	FL~FH	
35	FL	FL	Measure range low limit, the setting value must be less than measure range high limit	Refer to signal parameter table	-50
36	۶x	FH	Measure range high limit,the setting value must be more than measure range low limit.	Refer to signal parameter table	1200
37	6-C	BRL	The low limit of analog range, note: when this value is higher than high limit,it is reverse analog output.	FL~FH	-50
38	6 4 8	BRH	The high limit of analog range, note: when this value is lower the low limit, it is reverse analog output.	FL~FH	1200
39	6U	OLL	Output low limit, limit the output low limit current amplitude. Set value must be less than high limit.	-5.0~100.0	0
40	6UX	OLH	Output high limit,limit the output high limit current amplitude. Setting value must be larger than low limit.	0.0 ~ 105.0	100.0
41	SE	ST	Auto-tune function, 0: work normally after power on, 1: automatically enter PID parameters auto-tune status after power-on; long press "AT" key to exit auto-tune.	0~1	0
42	SPd	SPD	PID control speed adjustment,option: 0 (N) No , 1 (s) slow, 2 (ss) medium slow, 3(SSS)very slow, 4 (F) fast, 5 (FF) medium fast, 6 (FFF) very fast	0~6	Ν
43	980	PDC	PID algorithm option: 0(FUZ): Advanced fuzzy PID algorithm; 1(STD): normal PID algorithm	0~1	FUZ
44	P~5	PRS	Set the parameter save location: 0 (EEP): EEPROM has power-off protection;1 (RAM): RAM without power-off protection	EEP/RAM	EEP
45	-55	RSS	RUN/STOP save location: 0 (EEP): EEPROM has power-off protection;1 (RAM): RAM without power-off protection	EEP/RAM	EEP
46	P6	PT	Compressor start delay time, unit: s	0~9999	0
47	683	BAD	Baud 0 (4.8): 4800; 1 (9.6): 9600; 2 (19.2): 19200 3 (38.4): 38400; 4 (57.6): 57600; 5 (115.2): 115200	0~5	9.6

Con	tinued				
No.	Symbol	Name	Illustration	Setting range	Factory setting
48	866	ADD	Communication ADD	0~247	1
49	ዖራይሃ	PRTY	Communication parity check setting, 0:NO 1:ODD 2:EVEN	0~2	N0
50	35C	DTC	Communication data transport sequence 000; the 1st bit function reserved; the 2nd bit is byte sequence exchange; the 3rd bit function reserved.	Refer to COM. protocol note③	0
51	SP-E	SPRT	The set value of the heating slope, 0: Don't have this function, unit "C/minute. When the SPRT setting is valid, during PID operation, if the measured value is lower than the setting value, the temperature will be raised to the setting value using the SPRT defined heating rate limit value. Unit: per minute, if SPRT=5, the temperature will be raised to the setting value at 5 °C per minute.	0~9999	0
52	CRE	CAE	User self-calibration function, this parameter is only for the input signals except TC/RTD; Y:use the self-calibration parameters;N: Don' t use the self-calibration parameters.	0 (N) 1 (Y)	Ν
53	(8)	CAL	Self-calibration low limit input operation, after add the low end signal to the signal input terminal,flash YES to activate, after confirm and display OK, the input signal low end calibration is completed.	YES/OK	YES
54	СЯН	САН	Self-calibration high limit input operation, after add the high end signal to the signal input terminal,flash YES to activate, after confirm and display OK, the input signal high end calibration is completed.	YES/OK	YES
55	187	VER	Software version		

(1) Alarm parameters and output logic diagram:

Symbol description: " ${}_{\triangle}$ " means HY, " \blacktriangle " means alarm value, " ${}_{\triangle}$ " means SV value

•		
Alarm code	Alarm mode	Alarm output (AL1 & AL2 are independent from each) Image:the hatched section means the alarm action
0	Alarm close	
1	High limit absolute value alarm	
2	Low limit absolute value alarm	AL SV PV
3	%High limit deviation value alarm	→ PV
4	%Low limit deviation value alarm	SV-AL SV
5	%High/low limit deviation value alarm	SV-AL SV SV+AL
6	%High/low limit interval value alarm	→→ PV SV-AL SV SV+AL
7	High/low limit absolute value interval alarm	$\begin{array}{c c} & & & & & & \\ \hline & & & & & & & \\ \hline & & & &$
8	%High/ow limit deviation value interval alarm	<u>↓☆↓</u> svAl1 Sv sv+Al2 ≻PV
9	%High limit absolute value and low limit deviation value interval alarm	vst ALL SV ALL PV
10	%High limit deviation value and low limit absolute value interval alarm	→☆↑ AL1 SV SV+AL2 PV
11	%High/low limit absolute value alarm	Ata v v v v v v v v v v v v v v v v v v v
12	High/low limit deviation value alarm	→ → → → PV SV-AL1 SV SV+AL2

% For deviation alarm, if alarm value is set as a negative number, it will be used as an absolute value. Two groups of alarm parameters (AL1, AL2) below 7-12 are used in combination, AL1 alarm output, AD2 must be set to 0.

(2) Alarm extension function table

ı
alarm
eaches output.
output.
- r

X. Key function operation

1. RUN/Stop mode

Under the measure mode, press and hold "R/S" key > 3 sec to enter STOP mode, SV window will display "STOP", main control output stops or keep the minimum output.
 Under STOP mode, press and hold "R/S" key to exit STOP mode. Press " () key to

modify SV value. 3) Under STOP mode, alarm output and analog output work normally. 2. PID auto-tune operation:

- Before auto-tuning, please switch off the load power, or set the meter as STOP mode.
 Before auto-tuning, PV value should meet below condition: when it is PID heating control, PV needs to be much smaller than SV; when it is PID cooling control, PV needs to be much

greater than SV. 3) Before auto-tuning, please set a proper alarm value or eliminate the alarm condition, in order

(a) before auto-tuning, prease set a proper atarm value of entimate the atarm output.
(b) Set PID type and SV value; the factory default setting is fuzzy PID.
(c) Set as PID control, if there is OLL & OLH output limitation, please set the output to a proper range; factory default setting is OLL=0%. OLH=100%.
(c) Exit STOP mode, or switch on the load power, and immediately press and hold "AT" key to enter auto-tuning mode, then the AT indicator light is on.
(c) The output transport to the proper prot to affect output tune result please.

9) During the auto-tuning procedure will tak indicator light is off.
7) The auto-tuning procedure will tak some time, in order not to affect auto-tune result, please don't modify the parameters or power-off.
8) When AT light turns off, it automatically exits auto-tune mode, PID parameters will be updated automatically, and then the meter will control automatically and precisely.
9) During the auto-tuning procedure, below actions will cause the termination of the precess, press and hold "AT" key, measure beyond the scope, abnormal display, switch to STOP mode.

mode, power-off, etc. 10) Note: In the occasions with output limiting operation, sometimes, even if the auto-tuning is carried out, the best PID parameters still cannot be obtained.

11) Experienced users can set a proper PID parameter according to their experience.

- 3. PID heating and proportional cooling control operation
- Set the control mode OT as 3.
 PID heating control operates on OUT1; proportional cooling control operates on OUT2.
 Proportional cooling control OUT2 outputs via AL1 alarm function terminals.
- 4) Please set the cooling start hystersis DB to a value greater than 5, to ensure the cooling output will not affect the PID heating control. 5) Please set the cooling control cycle CP1 and the cooling proportionality coefficient PC to
- the proper value.
 6) When PV value > SV+DB value, the cooling control start to effect; the bigger value of PV, the longer output time of OUT2.
- 4. Auto-manual switch function
- 1) Enter common menu, set parameter A-M as "AM"
- 2) After return back to measure control interface, press " SET " key to switch auto-manual operation.
- When it is switched to manual control, lower line LED will display output percentage: M0~M100 (corresponding to 0%~100%), press UP key and DOWN key to modify the output
- 4) Before the switch from manual control to auto control, in order to ensure the smooth switch, please press Shift key to modify the SV value first.
 5) After the meter is rebooted, the default setting is manual control and output 0%.
- 5. Fixed manual control function 1) Set the A-M parameters to "MAN".
- After returning to the measurement control interface, the output volume can be manually adjusted.
 After powering on again, the manual output volume before power failure can be restored.
- 6. Linear signal self-calibration function
- Set the INP type and confirm it is one of 0~50mV, RT (0~400Ω), 4~20mA and 0~10V input.
- 2) Add the input signal to the correct input channel.3) Enter the menu lower limit calibration CAL, press "AT" to flash "YES"; and at this time, adjust the
- 4) When "YES" is flashing and the minimum signal value has been input to the instrument.
 4) When "YES" is flashing and the minimum signal value has been input to the instrument; press the "SET" key to confirm and save the calibration value.
 5) After calibrating the lower limit, enter the upper limit calibration menu CAH, and flash "YES" in
- the same way. 6) Adjust the input signal to the maximum value and input it into the instrument. And when "YES"
- flashes, press " SET " to confirm and save the calibration upper limit value. 7) After calibration, you can enter CAE and change "N" to "Y" to enable self-calibration; otherwise,
- use the factory calibration value. 8) The calibrated upper limit input linear signal value should not exceed the input standard value
- range ±10%. 9) If you are not satisfied with the calibration results after calibration, you can recalibrate

XI. Checking methods of simple fault

Display	Checking methods
LLLL/HHHH	Checks whether the input disconnection and whether normal of FH/ FL value, working environment temperature and whether input signal is selected correctly.
No display after power on	Check whether the voltage is normal; whether there is poor contact; internal protection for excessive grid harmonics;
No output	Check whether the wiring is correct; whether there is poor contact; whether the ACT/OT menu settings are incorrect;
No communication	Check hardware connection, instrument settings and software reading settings; hexadecimal conversion errors; address errors; data errors

XII Communication Protocol

The instrument uses Modbus RTU communication protocol, reads the function number 0x03 of the holding register in area 04, writes the function number 0x10 or 0x06, and uses 16-bit CRC for verification. The instrument does not return verification errors. The data type is a 16-bit signed or unsigned integer,

Data frame format

Start bit	Data bit	Stop bit	Check bit
1	8	1	None/odd parity/even parity

1. Read register

For example:Host reads integer SV(set value 200) The address code of SV is 0x2000, because SV is integer(2 dyte), seizes 1 data register. The memory code of decimal integer 200 is 0x00C8. Note: when reading data, should read DP value or confirm DP menu value first to ensure the decimal point postion, after that transform the read data to get the actual value. Conversely, it should transform the data to corresponding ratio before writing the data in meter.

Read multiple registers	Meter ADD	Function code	Start ADD high bit	Start ADD low bit	Data byte length high bit	Data byte length low bit	CRC code	CRC code
Host request	0x01	0x03	0x20	0x00	0x00	0x01	0x8F	0xCA
Slave responds normally	0x01	0x03	0x02 D	ata byte	0x00	0xC8	0xB9	0xD2
Slave responds abnormally	0x01	0x83	Example,	0x02 the host re	Error code equest addre	ss is 0x2011	0xC0	0xF1

Example: host writes multiple registers (using function code 10) to write the SV value (SV=150). The register address of SV is 0x2000, because the data type of SV is a 16-bit integer (2 bytes), 1 register. The decimal integer 150 is converted to hexadecimal code 0x0096. Before writing data, you should first convert the data to the corresponding magnification and then write the data to the instrument.

2. Write multiple registers

	Host request (write multiple registers)											
	Function code	ADD high bit	ADD low bit	Data high bit	Dat low	a bit	Data byte length	e Data high bit	Data low bit	CRC		CRC code
0x01	0x10	0x20	0x00	0x00	0x0	01	0x02	0x00	0x96	0x0	7	0xFC
			Slave	responds r	norma	ally (write multip	ple register	s)			
Mete ADD		ction e	Start ADD high bit	Start ADD low b		le	ata byte ngth gh bit	Data byte length low bit	e XCR0 code low bi	-	c	<crc ode igh bit</crc
0x0'	1 0x	10	0x20	0x00)		0x00	0x01	0x0/	۹.		0x09

Host writes single register (06 function code) writes SV value (SV=150)

Write single register	Meter ADD	Function code	ADD high bit	ADD low bit	Data high bit	Data low bit	CRC code	CRC code
Host request	0x01	0x06	0x20	0x00	0x00	0x96	0x02	0x64
Slave responds normally	0x01	0x06	0x20	0x00	0x00	0x96	0x02	0x64
Slave responds abnormally	0x01	0x86 Fund	ction code	0>	02 Error o	code	0xC3	0xA1

Communication abnormal handling method: When responding abnormally, set the highest bit of the function number to 1.

For example: if the function number requested by the host is 0x03, the corresponding function number returned by the slave is 0x83

0x01--Illegal function: The function number sent by the host is not supported by the instrument. 0x02--Illegal address: The register address specified by the host exceeds the allowable range of the instrument parameter address.

0x03--Illegal value: The write data value sent by the host exceeds the allowable range of the instrument. Meter parameters address mapping table

Meter	parameters addres	s mapping table			
No.	Add(Register No①)	Variable name	Register	R/W	Remark
1	0x2000 (48193)	Setting value SV	1	R/W	
2	0x2001 (48194)	1st alarm value AL1	1	R/W	
3	0x2002 (48195)	1st alarm hysteresis HY1	1	R/W	
4	0x2003 (48196)	2nd alarm value AL2	1	, R/W	
5	0x2004 (48197)	2nd alarm hysteresis HY2	1	R/W	
6	0x2005 (48198)	Display low limit FL	1	R/W	
7	0x2006 (48199)	Display high limit FH	1	R/W	
8	0x2007 (48200)	Analog output low limit BRL	1	R/W	
9	0x2007 (48200) 0x2008 (48201)	.	1	R/W	
10	0x2008 (48201)	Analog output high limit BRH			
11	(, , ,	Control output low limit OLL	1	R/W	Defects 4 also size al a size
12	0x200A (48203)	Control output high limit OLH		R/W	Default 1 decimal point
	0x200B (48204)	Overshoot limit OVS	1	R/W	
13	0x200C (48205)	Heat & Cool control dead zone DB	1	R/W	
14	0x200D (48206)	Proportional coefficient of cooling PC	1	R/W	Default 1 decimal point
15	0x200E (48207)	Amend value PS	1	R/W	Engineering work
16	0x200F (48208)	PV fuzzy tracking value DTR	1	R	without decimal point
17	0x2010 (48209)	Measured value PV	1	R	
18	0x2011 (48210)	Output percentage MV	1	R/W	0~100
19	0x2012 (48211)	Auto-Manual switch A-M	1	R/W	0:Auto; 1: Manual 2:Auto-Manual switch
20	0x2013 (48212)	3rd alarm value AL3	1	R/W	
21	0x2014 (48213)	3rd alarm hysteresis HY3	1	R/W	
22	0x2015 (48214)	Set value lower limit SLL	1	R/W	
23	0x2016 (48215)	Set value higher limit SLH	1	R/W	
24	0x2017 (48216)	Panel R/S operation switch SSM	1	R/W	
25	0x2018 (48217)	Set parameter storage location PRS	1	R/W	
26	0x2019 (48218)		1	R/W	
27	0x2019 (48218) 0x201A (48219)	RUN/STOP storage location RSS Slope display value SR-M	1	R	
28		Slope temperature rise set value SPRT	1	R/W	
20	0,2018 (40220)	Reserve	1	IV VV	
20	0.2100 (48440)	1st alarm mode AD1	1	R/W	
29	0x2100 (48449)				
30		2nd alarm mode AD2	1	R/W	
31	. ,	1st alarm extended function AE1	1	R/W	
32		2nd alarm extended function AE2	1	R/W	
33	0x2104 (48453)	Control mode OT	1	R/W	
34	0x2105 (48454)	Output mode ACT	1	R/W	
35	0x2106 (48455)	RUN/STOP operation	1	R/W	1:RUN 2:STP 3:Run auto-tune 4:Stop auto-tune
36	0x2107 (48456)	Decimal pointDP	1	R/W	
37	0x2108 (48457)	Unit display UT	1	R/W	25 (°C) 26 (°F)
38	0x2109 (48458)	Filter constants FT	1	R/W	
39	0x210A (48459)	Proportional coefficient P	1	R/W	No decimal point
40	0x210B (48460)	Integral time I	1	R/W	No decimal point
41	0x210C (48461)	Differential time D	1	R/W	No decimal point
42	0x210D (48462)	Control speed fine-tune SPD	1	R/W	
43		Heating control cycle CP	1	R/W	No decimal point
44	0x210F (48464)		1	R/W	No decimal point
45	0x2110 (48465)	Cooling delay time PT	1	R/W	No decimal point
46	0x2111 (48466)		1	R/W	Refer to signal table
47		Meter address ADD	1	R/W	
48	0x2112 (48467) 0x2113 (48468)	Communication baud rate BAD	1	R	
49	0x2113 (48468) 0x2114 (48469)	Comm. data transfer sequence DTC	1	R	Note3
49 50	0x2114 (48469) 0x2115 (48470)	PID arithmetic type PDC	1	R	140160
-			1	R	
51	0x2116 (48471)				
52	0x2117 (48472)		1	R	Nata
53	0x2118 (48473)		1	R	Note2
54	0x2119 (48474)	1 -	1	R	
55		3rd alarm mode AD3	1	R/W	
56	Ux211B (48476)	3rd alarm extended function AE3	1	R/W	1

R: Read only; R/W: Read & write

Note(): The register number is the address converted to decimal plus 1 and then the register identification code 4 is added in front; for example: the register number of the data address 0x2000 is 8192 + 1 = 8193 and then 4 is added in front, that is, the register number 48193; Related applications can be seen, such as Siemens S7-200 PLC. Note (): Measurement status indication. When the data bit is 1, it means execution, and when it is 0, it means no execution.

D8	D7	D6	D5	D4	D3	D2	D1	D0
AL3	STOP	НННН	LLLL	AT	AL2	AL1	OUT2	OUT1

Note(3): DTC communication data transmission sequence description

□ □ - Reserve

DTC:

Byte transfer order: when it is 0, the sequence is 1, 2; and when it is 1, the sequence is 2, 1 Reserve

XIII. Version and Revision History

Date	Version	Revision content
2024.06.14	A/0	1st edition